## Math 32404: Advanced Calculus II: Midterm 1 Review

## Material Covered: §8.2-8.5

**Definitions.** You will be asked to define several terms on the test. **These terms all have one definition, as given in the book. You are expected to know this definition.** The following is a list of terms which might appear. (Others might appear as well).

norm on a vector space, euclidean norm, operator norm, matrix, critical point, Lipschitz function (Example 7.5.13), change of basis, sup or max norm (Exercise 8.2.3),  $L^1$  norm (Exercise 8.2.4), eigenvalue and eigenvector, differentiable, derivative, partial derivative, gradient, curve, tangent vector, Jacobian determinant, continuously differentiable or  $C^1$ , locally invertible

## Comments

- The book defined eigenvalue on page 33, but didn't seem to define eigenvector. Supposing A is an  $n \times n$  matrix, a complex number  $\lambda \in C$  is an *eigenvector* if there is a non-zero vector  $x \in \mathbb{C}^n$  such that  $Ax = \lambda x$ . Any non-zero vector x such that there is a  $\lambda \in \mathbb{C}$  satisfying  $Ax = \lambda x$  is called an *eigenvector*.
- The book uses the term "locally invertible" but didn't formally define it. A function between metric spaces  $f : X \to Y$  is *locally invertible* at  $x \in X$  if there is an open set  $U \subset X$  such that  $x \in U$ , f(U) is open, and  $f|_U : U \to f(U)$  is a bijection. Local invertibility is a consequence of the Inverse function theorem.
- The book didn't seem to formally define critical point. A *critical point* of a differentiable function f is an x in the domain such that Df(x) is zero.

**Results you should know.** Below is a list of results you should know, and be able to apply. Results I think you should be able to prove are in bold. You will be asked to prove at least one of these results on the midterm.

Cauchy-Schwarz inequality (Lemma 7.1.4 and Thm 8.2.2), Properties of the operator norm in finite dimensional spaces (Props 8.2.4-5), The map  $A \mapsto A^{-1}$  is continuous (Prop 8.2.6), Properties of the determinant (Props 8.2.8-10), Uniqueness of the derivative (Prop 8.3.2), Differentiable implies continuous (Prop 8.3.5), The derivative is a linear operator (Prop 8.3.6), Matrix representation of the derivative (Prop. 8.3.9), Bounded derivative on a convex domain implies Lipschitz (Prop 8.4.2), Polynomials are  $C^1$ , Inverse function theorem, Implicit function theorem

Example questions: These are some problems I have written for exams in the past.

1. Are the functions below differentiable at 0? Justify your answer with a proof.

 $\mathbf{f}(x, y, z) = \sqrt[3]{xyz}$  and  $\mathbf{g}(x, y, z) = \sqrt[3]{x^2yz}$ .

- 2. Let g(a, b, c) be a  $C^2$  function  $\mathbb{R}^3 \to \mathbb{R}$ . Let  $f(x, y) = g(x^2, xy, y^2)$ .
  - (a) Compute  $\frac{\partial f}{\partial x}(x, y)$  in terms of x, y and partial derivatives of g.
  - (b) Compute  $\frac{\partial^2 f}{\partial y \partial x}(x, y)$  in terms of x, y and partial derivatives of g.
- 3. (a) Complete the following definition. Let  $S \subset \mathbb{R}^n$  be an open set. The function  $f: S \to \mathbb{R}$  is differentiable at  $\mathbf{a} \in S$  if
  - (b) Suppose  $f : \mathbb{R}^2 \to \mathbb{R}$  satisfies f(0,0) = 0 and

$$x - x^2 - y^2 \le f(x, y) \le x + x^2 + y^2$$
 for all  $(x, y) \in \mathbb{R}^2$ .

Prove that f is differentiable at (0, 0).

- 4. Show that the two side-lengths of an isosceles triangle can be expressed as a function of the perimeter and area of the triangle locally near any non-equilateral isosceles triangle.
- 5. Suppose  $f : \mathbb{R}^2 \to \mathbb{R}^2$  is a differentiable function. Define g(x, y) = |f(x, y)| where  $|\cdot|$  denotes the Euclidean norm.
  - (a) Give a formula for  $\nabla g(x, y)$  at any point (x, y) for which  $f(x, y) \neq (0, 0)$ . Your formula should be in terms of x, y, the entries of f(x, y), and the partial derivatives of the two component functions of f.
  - (b) Show that if Df(x, y) is the zero matrix, then (x, y) is a critical point of g. That is, show that Df(x, y) = 0 implies that Dg(x, y) = 0.
- 6. Let  $\alpha : \mathbb{R} \to \mathbb{R}^3$  be a parameterized  $C^1$  path in the plane z = 0 and let  $\beta : \mathbb{R} \to \mathbb{R}^3$  be a parameterized  $C^1$  path in the plane z = 1. Define

 $F : \mathbb{R}^3 \to \mathbb{R}^3$  by  $F(s,t,z) = \alpha(s) + z(\beta(t) - \alpha(s)).$ 

Then, when s and t are held constant, the map  $z \mapsto F(s,t,z)$  parameterizes the line joining  $\alpha(s)$  to  $\beta(t)$ .

- (a) Use the Inverse Function Theorem to show that if  $z_0 \notin \{0,1\}$  and  $\alpha'(s_0)$  and  $\beta'(t_0)$  are not parallel, then F is invertible in a neighborhood of the point  $(s_0, t_0, z_0)$  in the domain.
- 7. Let  $\mathbf{G}(u, v) = (uv 3, u^2 + 2v).$ 
  - (a) Suppose V is an open neighborhood of  $(-3, 6) \in \mathbb{R}^2$  and that  $\mathbf{H} : V \to \mathbb{R}^2$  is a map so that  $\mathbf{G} \circ \mathbf{H}(x, y) = (x, y)$  for all  $(x, y) \in V$ . (**H** is a local inverse to **G** at (0, 3).) Find the matrix of partial derivatives  $D\mathbf{H}(-3, 6)$ .
  - (b) Let  $B_{\epsilon}$  denote the open ball of radius  $\epsilon$  at (0,3). Estimate the quantity

Area 
$$\mathbf{G}(B_{\epsilon})/\text{Area } B_{\epsilon}$$

for  $\epsilon$  small. (Concretely, what is the limit of this ratio as  $\epsilon \to 0$ ?)