

Billiards in right triangles are unstable

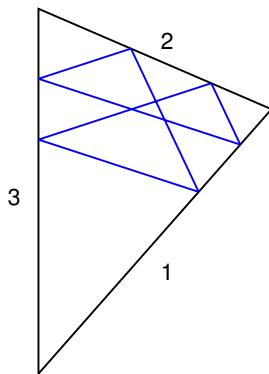
W. Patrick Hooper

Northwestern University

Geometry, Dynamics and Topology Day
Eastern Illinois University
October 27, 2007

Comparing billiard paths in different triangles

- Mark the edges of our triangles by $\{1, 2, 3\}$.
- The **orbit-type** $\mathcal{O}(\hat{\gamma})$ of a periodic billiard path $\hat{\gamma}$ is the bi-infinite periodic sequence of markings corresponding to the edges hit.



A periodic billiard path $\hat{\gamma}$ with orbit type $\mathcal{O}(\hat{\gamma}) = \overline{123123}$.

Comparing billiard paths in different triangles

Open Question

Does every triangle have a periodic billiard path?

Comparing billiard paths in different triangles

Open Question

Does every triangle have a periodic billiard path?

- Let \mathcal{T} be the space of marked triangles up to similarities preserving the markings.
- We coordinatize \mathcal{T} by the angles of the triangles:

$$\mathcal{T} = \{(\alpha_1, \alpha_2, \alpha_3) \in \mathbb{R}^3 \mid \alpha_1 + \alpha_2 + \alpha_3 = \pi \text{ and each } \alpha_j > 0\}.$$

Comparing billiard paths in different triangles

Open Question

Does every triangle have a periodic billiard path?

- Let \mathcal{T} be the space of marked triangles up to similarities preserving the markings.
- We coordinatize \mathcal{T} by the angles of the triangles:

$$\mathcal{T} = \{(\alpha_1, \alpha_2, \alpha_3) \in \mathbb{R}^3 \mid \alpha_1 + \alpha_2 + \alpha_3 = \pi \text{ and each } \alpha_j > 0\}.$$

- The **tile** of a periodic billiard path $\hat{\gamma}$ is the subset $\text{tile}(\hat{\gamma}) \subset \mathcal{T}$ consisting of all triangles $\Delta \in \mathcal{T}$ with periodic billiard paths $\hat{\eta}$ with the same orbit type as $\hat{\gamma}$.

Comparing billiard paths in different triangles

Open Question

Does every triangle have a periodic billiard path?

- Let \mathcal{T} be the space of marked triangles up to similarities preserving the markings.
- We coordinatize \mathcal{T} by the angles of the triangles:

$$\mathcal{T} = \{(\alpha_1, \alpha_2, \alpha_3) \in \mathbb{R}^3 \mid \alpha_1 + \alpha_2 + \alpha_3 = \pi \text{ and each } \alpha_i > 0\}.$$

- The **tile** of a periodic billiard path $\hat{\gamma}$ is the subset $\text{tile}(\hat{\gamma}) \subset \mathcal{T}$ consisting of all triangles $\Delta \in \mathcal{T}$ with periodic billiard paths $\hat{\eta}$ with the same orbit type as $\hat{\gamma}$.
- The question above becomes equivalent to “Can \mathcal{T} be covered by tiles?”

Theorem (Classification of tiles)

Let $\hat{\gamma}$ be a periodic billiard path in a triangle Δ . Then either

- 1 $\text{tile}(\hat{\gamma})$ is an open subset of \mathcal{T} , or
- 2 $\text{tile}(\hat{\gamma})$ is an open subset of a **rational line** of the form

$$\{(\alpha_1, \alpha_2, \alpha_3) \in \mathcal{T} \mid n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0\}$$

for some integers n_1, n_2, n_3 (not all zero).

Theorem (Classification of tiles)

Let $\hat{\gamma}$ be a periodic billiard path in a triangle Δ . Then either

- 1 $\text{tile}(\hat{\gamma})$ is an open subset of \mathcal{T} , or
- 2 $\text{tile}(\hat{\gamma})$ is an open subset of a **rational line** of the form

$$\{(\alpha_1, \alpha_2, \alpha_3) \in \mathcal{T} \mid n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0\}$$

for some integers n_1, n_2, n_3 (not all zero).

- In the first case, $\hat{\gamma}$ is called **stable**. In any sufficiently small perturbation of Δ , we can find a periodic billiard path with the same orbit-type.

Theorem (Classification of tiles)

Let $\hat{\gamma}$ be a periodic billiard path in a triangle Δ . Then either

- 1 $\text{tile}(\hat{\gamma})$ is an open subset of \mathcal{T} , or
- 2 $\text{tile}(\hat{\gamma})$ is an open subset of a **rational line** of the form

$$\{(\alpha_1, \alpha_2, \alpha_3) \in \mathcal{T} \mid n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0\}$$

for some integers n_1, n_2, n_3 (not all zero).

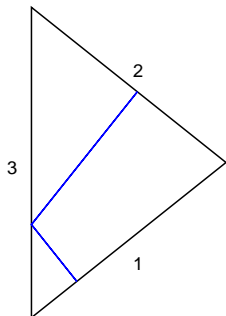
- In the first case, $\hat{\gamma}$ is called **stable**. In any sufficiently small perturbation of Δ , we can find a periodic billiard path with the same orbit-type.
- Almost every triangle only has stable periodic billiard paths!
- But for example, right triangles may have unstable periodic billiard paths. Since if $\alpha_1 = \frac{\pi}{2}$, then

$$\alpha_1 - \alpha_2 - \alpha_3 = 0.$$

Example of an unstable periodic billiard path

- A periodic billiard path $\hat{\gamma}$ with orbit type $\mathcal{O}(\hat{\gamma}) = \overline{1323}$ is unstable.
- By similar triangles, $\text{tile}(\hat{\gamma})$ is the collection of isosceles triangles with base marked '3'.

$$\text{tile}(\hat{\gamma}) = \{(\alpha_1, \alpha_2, \alpha_3) \in \mathcal{T} \mid \alpha_1 - \alpha_2 = 0\}.$$



Theorems on stability in right triangles

The following settles a conjecture of Vorobets, Galperin, and Stepin.

Theorem (H)

Right triangles do not have stable periodic billiard paths.

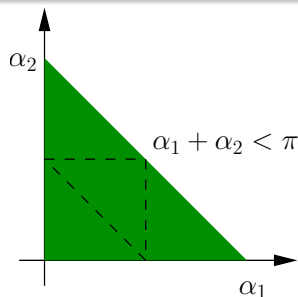
Theorems on stability in right triangles

The following settles a conjecture of Vorobets, Galperin, and Stepin.

Theorem (H)

Right triangles do not have stable periodic billiard paths.

Let $\mathcal{R} \subset \mathcal{T}$ denote the collection of right triangles.



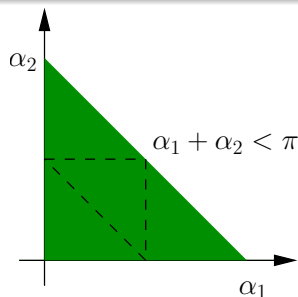
Theorems on stability in right triangles

The following settles a conjecture of Vorobets, Galperin, and Stepin.

Theorem (H)

Right triangles do not have stable periodic billiard paths.

Let $\mathcal{R} \subset \mathcal{T}$ denote the collection of right triangles.

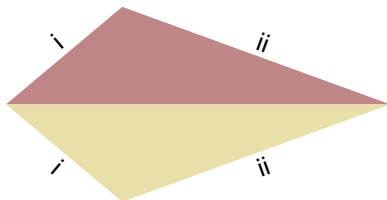


Theorem (H)

If $\hat{\gamma}$ is a stable periodic billiard path in a triangle, then $\text{tile}(\hat{\gamma})$ is contained in one of the connected components of $\mathcal{T} \setminus \mathcal{R}$.

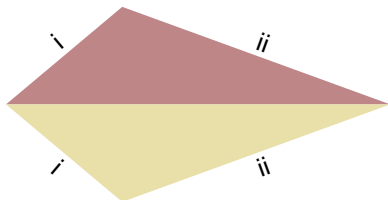
When are billiard paths stable? (1 of 4)

- Given a triangle Δ we can build a Euclidean cone surface $\mathcal{D}(\Delta)$ by doubling the triangle across its boundary. (A triangular pillowcase.)
- Let Σ denote the collection of cone singularities on $\mathcal{D}(\Delta)$.



When are billiard paths stable? (1 of 4)

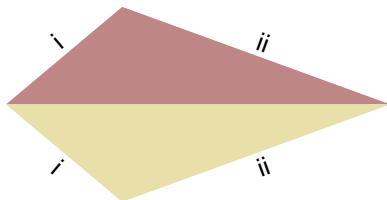
- Given a triangle Δ we can build a Euclidean cone surface $\mathcal{D}(\Delta)$ by doubling the triangle across its boundary. (A triangular pillowcase.)
- Let Σ denote the collection of cone singularities on $\mathcal{D}(\Delta)$.



- There is a natural folding (or ironing) map $\mathcal{D}(\Delta) \rightarrow \Delta$.

When are billiard paths stable? (1 of 4)

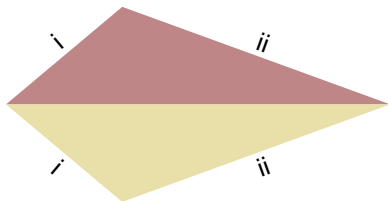
- Given a triangle Δ we can build a Euclidean cone surface $\mathcal{D}(\Delta)$ by doubling the triangle across its boundary. (A triangular pillowcase.)
- Let Σ denote the collection of cone singularities on $\mathcal{D}(\Delta)$.



- There is a natural folding (or ironing) map $\mathcal{D}(\Delta) \rightarrow \Delta$.
- The billiard flow on Δ can be pulled back to the geodesic flow on $\mathcal{D}(\Delta) \setminus \Sigma$.

When are billiard paths stable? (1 of 4)

- Given a triangle Δ we can build a Euclidean cone surface $\mathcal{D}(\Delta)$ by doubling the triangle across its boundary. (A triangular pillowcase.)
- Let Σ denote the collection of cone singularities on $\mathcal{D}(\Delta)$.



- There is a natural folding (or ironing) map $\mathcal{D}(\Delta) \rightarrow \Delta$.
- The billiard flow on Δ can be pulled back to the geodesic flow on $\mathcal{D}(\Delta) \setminus \Sigma$.
- Each periodic billiard path $\hat{\gamma}$ on Δ pulls back to a closed geodesic γ on $\mathcal{D}(\Delta)$.

When are billiard paths stable? (2 of 4)

- Let $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ be the function which measures angle.

When are billiard paths stable? (2 of 4)

- Let $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ be the function which measures angle.
- The closed 1-form $d\theta$ on $T_1\mathbb{R}^2$ is invariant under the action of $\text{Isom}_+(\mathbb{R}^2)$.

When are billiard paths stable? (2 of 4)

- Let $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ be the function which measures angle.
- The closed 1-form $d\theta$ on $T_1\mathbb{R}^2$ is invariant under the action of $\text{Isom}_+(\mathbb{R}^2)$.
- It pulls back to closed 1-form on the unit tangent bundle of any locally Euclidean surface.

When are billiard paths stable? (2 of 4)

- Let $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ be the function which measures angle.
- The closed 1-form $d\theta$ on $T_1\mathbb{R}^2$ is invariant under the action of $\text{Isom}_+(\mathbb{R}^2)$.
- It pulls back to closed 1-form on the unit tangent bundle of any locally Euclidean surface.
- If γ is a closed geodesic on a locally Euclidean surface then

$$\int_{\gamma'} d\theta = 0.$$

When are billiard paths stable? (2 of 4)

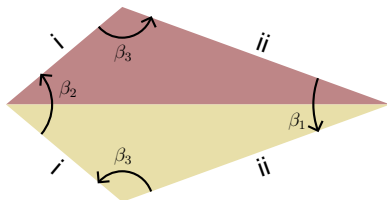
- Let $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ be the function which measures angle.
- The closed 1-form $d\theta$ on $T_1\mathbb{R}^2$ is invariant under the action of $\text{Isom}_+(\mathbb{R}^2)$.
- It pulls back to closed 1-form on the unit tangent bundle of any locally Euclidean surface.
- If γ is a closed geodesic on a locally Euclidean surface then

$$\int_{\gamma'} d\theta = 0.$$

- Because $d\theta$ is closed, this is a homological invariant of the curve γ' in the unit tangent bundle.

When are billiard paths stable? (3 of 4)

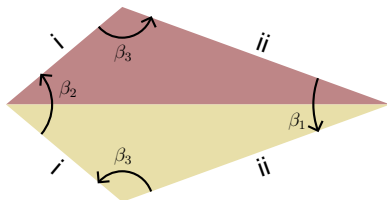
- In our case, the surface is the double of a triangle $\mathcal{D}(\Delta)$.



- The homology group of the unit tangent bundle, $H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z}) \cong \mathbb{Z}^3$, is generated by derivatives of curves which travel around the punctures.

When are billiard paths stable? (3 of 4)

- In our case, the surface is the double of a triangle $\mathcal{D}(\Delta)$.



- The homology group of the unit tangent bundle, $H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z}) \cong \mathbb{Z}^3$, is generated by derivatives of curves which travel around the punctures.
- If $[[x]] = n_1\beta'_1 + n_2\beta'_2 + n_3\beta'_3 \in H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z})$ then

$$\int_{[[x]]} d\theta = 2n_1\alpha_1 + 2n_2\alpha_2 + 2n_3\alpha_3.$$

When are billiard paths stable? (4 of 4)

- Consequently, in order for a homology class $[[x]] = n_1\beta'_1 + n_2\beta'_2 + n_3\beta'_3 \in H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z})$ to contain the derivative of a closed geodesic, it must be

$$n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0.$$

When are billiard paths stable? (4 of 4)

- Consequently, in order for a homology class $[[x]] = n_1\beta'_1 + n_2\beta'_2 + n_3\beta'_3 \in H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z})$ to contain the derivative of a closed geodesic, it must be

$$n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0.$$

- Suppose, $\hat{\gamma}$ is a stable periodic billiard path. Let γ be the pull back to $\mathcal{D}(\Delta)$. Then γ' must be homologous to zero in $T_1\mathcal{D}(\Delta) \setminus \Sigma$.

When are billiard paths stable? (4 of 4)

- Consequently, in order for a homology class $[[x]] = n_1\beta'_1 + n_2\beta'_2 + n_3\beta'_3 \in H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z})$ to contain the derivative of a closed geodesic, it must be

$$n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0.$$

- Suppose, $\hat{\gamma}$ is a stable periodic billiard path. Let γ be the pull back to $\mathcal{D}(\Delta)$. Then γ' must be homologous to zero in $T_1\mathcal{D}(\Delta) \setminus \Sigma$.
- **Remark:** In fact, this is a sufficient condition for stability. This can be seen by checking that all remaining conditions for a homotopy class in $\mathcal{D}(\Delta) \setminus \Sigma$ to contain a geodesic are open conditions.

When are billiard paths stable? (4 of 4)

- Consequently, in order for a homology class $[[x]] = n_1\beta'_1 + n_2\beta'_2 + n_3\beta'_3 \in H_1(T_1\mathcal{D}(\Delta) \setminus \Sigma, \mathbb{Z})$ to contain the derivative of a closed geodesic, it must be

$$n_1\alpha_1 + n_2\alpha_2 + n_3\alpha_3 = 0.$$

- Suppose, $\hat{\gamma}$ is a stable periodic billiard path. Let γ be the pull back to $\mathcal{D}(\Delta)$. Then γ' must be homologous to zero in $T_1\mathcal{D}(\Delta) \setminus \Sigma$.
- **Remark:** In fact, this is a sufficient condition for stability. This can be seen by checking that all remaining conditions for a homotopy class in $\mathcal{D}(\Delta) \setminus \Sigma$ to contain a geodesic are open conditions.

Theorem (Classification of tiles)

Let $\hat{\gamma}$ be a periodic billiard path in a triangle Δ . Then $\text{tile}(\hat{\gamma})$ is stable iff γ' is null homologous. Otherwise, $\text{tile}(\hat{\gamma})$ is an open subset of a rational line.

Translation surfaces (1 of 2)

- A **translation surface** is a Euclidean cone surface whose cone angles are all in $2\pi\mathbb{N} \cup \{\infty\}$.
- These surfaces appear naturally from the point of view of the previous discussion.

Translation surfaces (1 of 2)

- A **translation surface** is a Euclidean cone surface whose cone angles are all in $2\pi\mathbb{N} \cup \{\infty\}$.
- These surfaces appear naturally from the point of view of the previous discussion.
- Consider the group homomorphism

$$\Theta : \pi_1(T_1\mathcal{D}(\Delta) \setminus \Sigma) \rightarrow \mathbb{R} : [x] \mapsto \int_x d\theta.$$

- Let $\phi : T_1\mathcal{D}(\Delta) \setminus \Sigma \rightarrow \mathcal{D}(\Delta) \setminus \Sigma$.
- Let $G = \phi_*(\ker \Theta) \subset \pi_1(\mathcal{D}(\Delta) \setminus \Sigma)$.

Translation surfaces (1 of 2)

- A **translation surface** is a Euclidean cone surface whose cone angles are all in $2\pi\mathbb{N} \cup \{\infty\}$.
- These surfaces appear naturally from the point of view of the previous discussion.
- Consider the group homomorphism

$$\Theta : \pi_1(T_1\mathcal{D}(\Delta) \setminus \Sigma) \rightarrow \mathbb{R} : [x] \mapsto \int_x d\theta.$$

- Let $\phi : T_1\mathcal{D}(\Delta) \setminus \Sigma \rightarrow \mathcal{D}(\Delta) \setminus \Sigma$.
- Let $G = \phi_*(\ker \Theta) \subset \pi_1(\mathcal{D}(\Delta) \setminus \Sigma)$.
- A homotopy class $[\gamma]$ in $\mathcal{D}(\Delta) \setminus \Sigma$ must lie in G in order to contain a geodesic.

Translation surfaces (1 of 2)

- A **translation surface** is a Euclidean cone surface whose cone angles are all in $2\pi\mathbb{N} \cup \{\infty\}$.
- These surfaces appear naturally from the point of view of the previous discussion.
- Consider the group homomorphism

$$\Theta : \pi_1(T_1\mathcal{D}(\Delta) \setminus \Sigma) \rightarrow \mathbb{R} : [x] \mapsto \int_x d\theta.$$

- Let $\phi : T_1\mathcal{D}(\Delta) \setminus \Sigma \rightarrow \mathcal{D}(\Delta) \setminus \Sigma$.
- Let $G = \phi_*(\ker \Theta) \subset \pi_1(\mathcal{D}(\Delta) \setminus \Sigma)$.
- A homotopy class $[\gamma]$ in $\mathcal{D}(\Delta) \setminus \Sigma$ must lie in G in order to contain a geodesic.
- The cover of $\mathcal{D}(\Delta)$ branched over Σ associated to G is a translation surface $MT(\Delta)$.

Translation surfaces (2 of 2)

- We call $MT(\Delta)$ the minimal translation surface cover of $\mathcal{D}(\Delta)$.

Translation surfaces (2 of 2)

- We call $MT(\Delta)$ the minimal translation surface cover of $\mathcal{D}(\Delta)$.
- We will now describe a less technical definition of $MT(\Delta)$.

Translation surfaces (2 of 2)

- We call $MT(\Delta)$ the minimal translation surface cover of $\mathcal{D}(\Delta)$.
- We will now describe a less technical definition of $MT(\Delta)$.
- Let H be the group $\mathbb{Z}_2 * \mathbb{Z}_2 * \mathbb{Z}_2$ generated by r_1, r_2, r_3 .
- Let $\rho : H \rightarrow \text{Isom } \mathbb{R}^2$ which sends each generator r_i to reflection in the i -th side of Δ .
- $MT(\Delta)$ is $\{h(\Delta) \mid h \in H\}$ with some identifications:

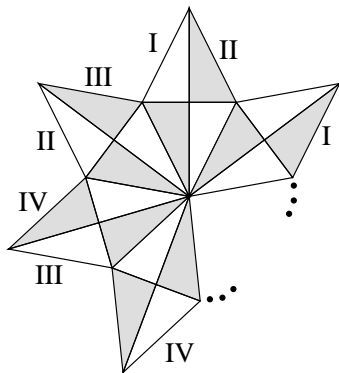
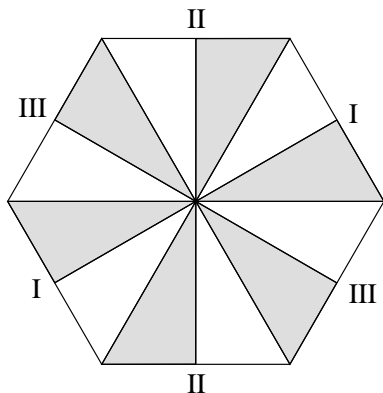
Translation surfaces (2 of 2)

- We call $MT(\Delta)$ the minimal translation surface cover of $\mathcal{D}(\Delta)$.
- We will now describe a less technical definition of $MT(\Delta)$.
- Let H be the group $\mathbb{Z}_2 * \mathbb{Z}_2 * \mathbb{Z}_2$ generated by r_1, r_2, r_3 .
- Let $\rho : H \rightarrow \text{Isom } \mathbb{R}^2$ which sends each generator r_i to reflection in the i -th side of Δ .
- $MT(\Delta)$ is $\{h(\Delta) \mid h \in H\}$ with some identifications:
 - 1 Identify $h_1(\Delta)$ and $h_2(\Delta)$ along the edge i if $h_1 \circ h_2^{-1} = r_i$.

Translation surfaces (2 of 2)

- We call $MT(\Delta)$ the minimal translation surface cover of $\mathcal{D}(\Delta)$.
- We will now describe a less technical definition of $MT(\Delta)$.
- Let H be the group $\mathbb{Z}_2 * \mathbb{Z}_2 * \mathbb{Z}_2$ generated by r_1, r_2, r_3 .
- Let $\rho : H \rightarrow \text{Isom } \mathbb{R}^2$ which sends each generator r_i to reflection in the i -th side of Δ .
- $MT(\Delta)$ is $\{h(\Delta) \mid h \in H\}$ with some identifications:
 - 1 Identify $h_1(\Delta)$ and $h_2(\Delta)$ along the edge i if $h_1 \circ h_2^{-1} = r_i$.
 - 2 Identify triangles $h_1(\Delta)$ and $h_2(\Delta)$ if $\rho(h_1 \circ h_2^{-1})$ is a translation.

Example minimal translation surfaces



- The minimal translation surface for the 30-60-90 triangle is a hexagonal torus.
- The minimal translation surface of a right triangle whose other angles are not rational multiples of π is an infinite union of rombi.

Closed geodesics on translation surfaces

- Every closed geodesic on a Euclidean cone surface $\mathcal{D}(\Delta)$ lifts to the minimal translation surface cover of $MT(\Delta)$.

Closed geodesics on translation surfaces

- Every closed geodesic on a Euclidean cone surface $\mathcal{D}(\Delta)$ lifts to the minimal translation surface cover of $MT(\Delta)$.
- The direction map $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ lifts to a map $\theta : T_1MT(\Delta) \rightarrow \mathbb{R}/2\pi\mathbb{Z}$.

Closed geodesics on translation surfaces

- Every closed geodesic on a Euclidean cone surface $\mathcal{D}(\Delta)$ lifts to the minimal translation surface cover of $MT(\Delta)$.
- The direction map $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ lifts to a map $\theta : T_1MT(\Delta) \rightarrow \mathbb{R}/2\pi\mathbb{Z}$.
- The direction map θ is invariant under the geodesic flow. Thus, closed geodesics on $MT(\Delta)$ never intersect.

Closed geodesics on translation surfaces

- Every closed geodesic on a Euclidean cone surface $\mathcal{D}(\Delta)$ lifts to the minimal translation surface cover of $MT(\Delta)$.
- The direction map $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ lifts to a map $\theta : T_1MT(\Delta) \rightarrow \mathbb{R}/2\pi\mathbb{Z}$.
- The direction map θ is invariant under the geodesic flow. Thus, closed geodesics on $MT(\Delta)$ never intersect.
- Moreover, two geodesics which travel in the same direction can not intersect.

Closed geodesics on translation surfaces

- Every closed geodesic on a Euclidean cone surface $\mathcal{D}(\Delta)$ lifts to the minimal translation surface cover of $MT(\Delta)$.
- The direction map $\theta : T_1\mathbb{R}^2 \rightarrow \mathbb{R}/2\pi\mathbb{Z}$ lifts to a map $\theta : T_1MT(\Delta) \rightarrow \mathbb{R}/2\pi\mathbb{Z}$.
- The direction map θ is invariant under the geodesic flow. Thus, closed geodesics on $MT(\Delta)$ never intersect.
- Moreover, two geodesics which travel in the same direction can not intersect.
- This is the main idea behind the proof of

Theorem

Right triangles don't have stable periodic billiard paths.

We will now discuss the proof.

No stable trajectories (1 of 4)

- It is sufficient to prove that a right triangle Δ whose other angles are not rational multiples of π has no stable periodic billiard paths.

No stable trajectories (1 of 4)

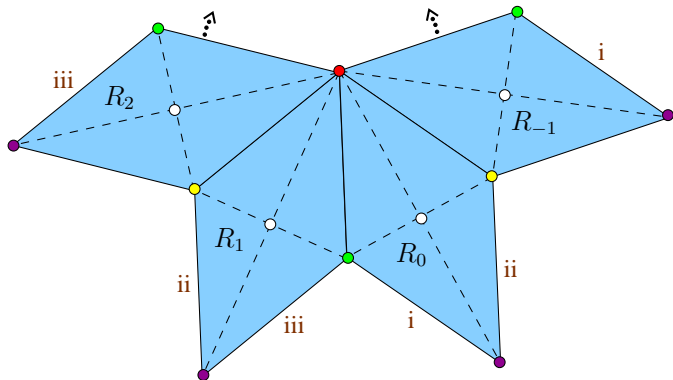
- It is sufficient to prove that a right triangle Δ whose other angles are not rational multiples of π has no stable periodic billiard paths.
- A periodic billiard path $\hat{\gamma}$ in Δ lifts to a closed geodesic γ in $\mathcal{D}(\Delta)$.

No stable trajectories (1 of 4)

- It is sufficient to prove that a right triangle Δ whose other angles are not rational multiples of π has no stable periodic billiard paths.
- A periodic billiard path $\hat{\gamma}$ in Δ lifts to a closed geodesic γ in $\mathcal{D}(\Delta)$.
- γ lifts to a closed geodesic $\tilde{\gamma}$ in $MT(\Delta)$.

No stable trajectories (1 of 4)

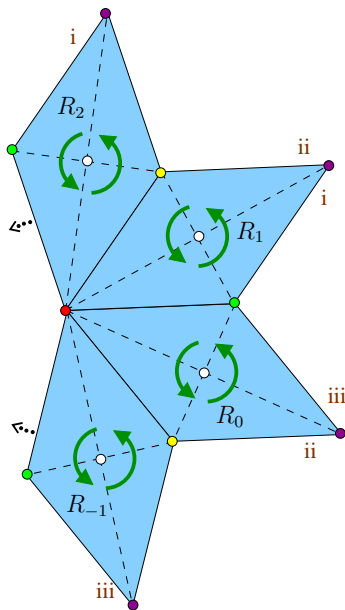
- It is sufficient to prove that a right triangle Δ whose other angles are not rational multiples of π has no stable periodic billiard paths.
- A periodic billiard path $\hat{\gamma}$ in Δ lifts to a closed geodesic γ in $\mathcal{D}(\Delta)$.
- γ lifts to a closed geodesic $\tilde{\gamma}$ in $MT(\Delta)$.



No stable trajectories (2 of 4)

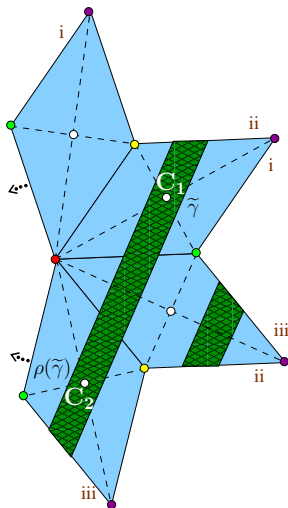
- $MT(\Delta)$ supports a rotation by π , ρ , which preserves each rhombus.
- This rotation by π , ρ , is an automorphism of the cover

$$MT(\Delta) \rightarrow \mathcal{D}(\Delta)$$

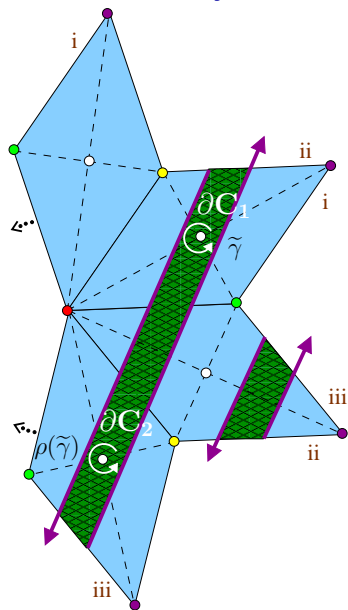


No stable trajectories (3 of 4)

- **Sketch of proof:** Right triangles only have unstable periodic billiard paths.
- We will show that the pair of curves $\tilde{\gamma}$ and $\rho(\tilde{\gamma})$ bound a cylinder in $MT(\Delta)$ containing two centers of rhombi, C_1 and C_2 .



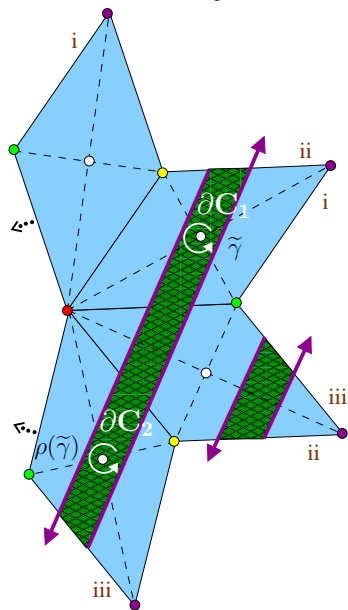
No stable trajectories (4 of 4)



- Then in homology on MT_{Δ} ,

$$[[\tilde{\gamma}]] + [[\rho(\tilde{\gamma})]] = [[\partial C_1]] + [[\partial C_2]]$$

No stable trajectories (4 of 4)



- Then in homology on MT_Δ ,

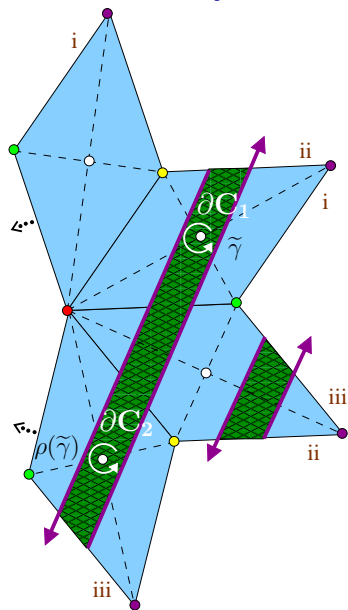
$$[[\tilde{\gamma}]] + [[\rho(\tilde{\gamma})]] = [[\partial C_1]] + [[\partial C_2]]$$

- Under the covering map

$$\phi : MT_\Delta \rightarrow \mathcal{D}_\Delta,$$

$$\triangleright \phi([[\tilde{\gamma}]]) = \phi([[\rho(\tilde{\gamma})]]) = [[\gamma]]$$

No stable trajectories (4 of 4)



- Then in homology on MT_{Δ} ,

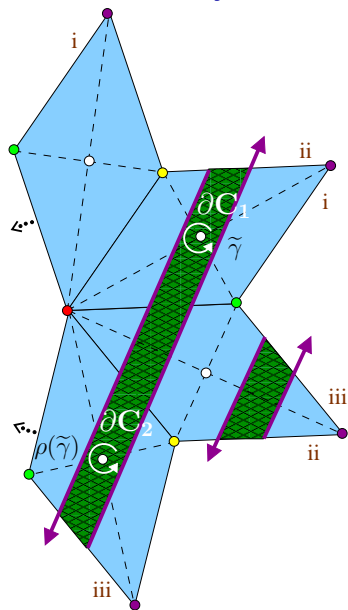
$$[[\tilde{\gamma}]] + [[\rho(\tilde{\gamma})]] = [[\partial C_1]] + [[\partial C_2]]$$

- Under the covering map

$$\phi : MT_{\Delta} \rightarrow \mathcal{D}_{\Delta},$$

- ▶ $\phi([[\tilde{\gamma}]]) = \phi([[\rho(\tilde{\gamma})]]) = [[\gamma]]$
- ▶ $\phi([[\partial C_1]]) = \phi([[\partial C_2]])$

No stable trajectories (4 of 4)



- Then in homology on MT_{Δ} ,

$$[[\tilde{\gamma}]] + [[\rho(\tilde{\gamma})]] = [[\partial C_1]] + [[\partial C_2]]$$

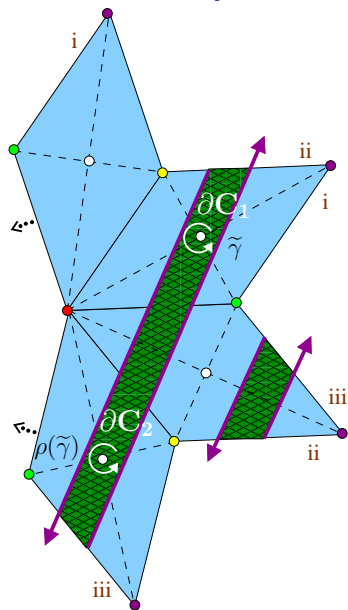
- Under the covering map

$$\phi : MT_{\Delta} \rightarrow \mathcal{D}_{\Delta},$$

- ▶ $\phi([[\tilde{\gamma}]]) = \phi([[\rho(\tilde{\gamma})]]) = [[\gamma]]$
- ▶ $\phi([[\partial C_1]]) = \phi([[\partial C_2]])$
- ▶ Thus,

$$[[\gamma]] = \phi([[\partial C_1]]) \neq 0$$

No stable trajectories (4 of 4)



- Then in homology on MT_{Δ} ,

$$[[\tilde{\gamma}]] + [[\rho(\tilde{\gamma})]] = [[\partial C_1]] + [[\partial C_2]]$$

- Under the covering map

$$\phi : MT_{\Delta} \rightarrow \mathcal{D}_{\Delta},$$

- ▶ $\phi([[\tilde{\gamma}]]) = \phi([[\rho(\tilde{\gamma})]]) = [[\gamma]]$
- ▶ $\phi([[\partial C_1]]) = \phi([[\partial C_2]])$
- ▶ Thus,

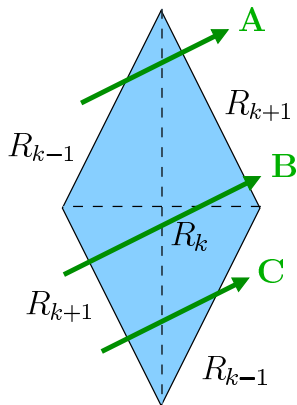
$$[[\gamma]] = \phi([[\partial C_1]]) \neq 0$$

- The geodesic γ is **unstable**!

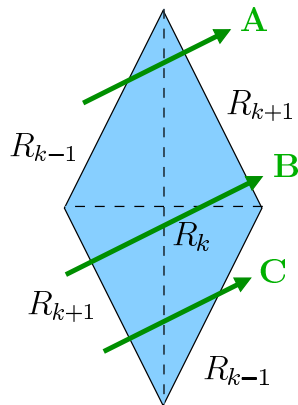
Finding the cylinder (1 of 3)

Claim 1: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ intersects each edge of each rhombus an even number of times.

Proof:



Finding the cylinder (1 of 3)

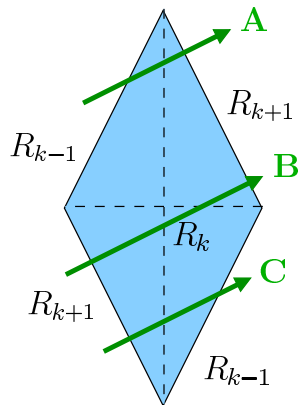


Claim 1: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ intersects each edge of each rhombus an even number of times.

Proof:

- Fixing the direction $\tilde{\gamma}$ travels, there are only 3 possible ways $\tilde{\gamma}$ can cross each rhombus R_k .

Finding the cylinder (1 of 3)

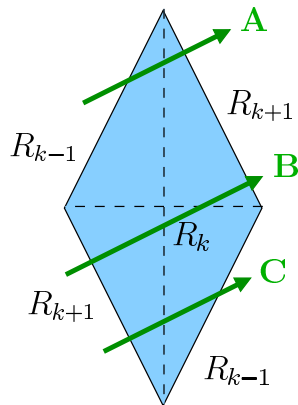


Claim 1: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ intersects each edge of each rhombus an even number of times.

Proof:

- Fixing the direction $\tilde{\gamma}$ travels, there are only 3 possible ways $\tilde{\gamma}$ can cross each rhombus R_k .
- The claim is equivalent to showing that the number of type **A** crossings of $\tilde{\gamma}$ equals the number of type **C** crossings of $\tilde{\gamma}$.

Finding the cylinder (1 of 3)

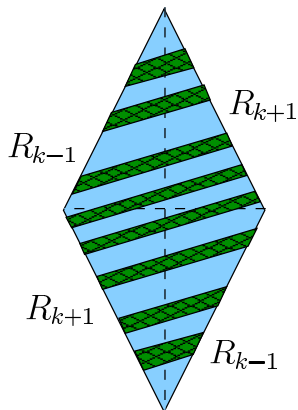


Claim 1: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ intersects each edge of each rhombus an even number of times.

Proof:

- Fixing the direction $\tilde{\gamma}$ travels, there are only 3 possible ways $\tilde{\gamma}$ can cross each rhombus R_k .
- The claim is equivalent to showing that the number of type **A** crossings of $\tilde{\gamma}$ equals the number of type **C** crossings of $\tilde{\gamma}$.
- But, $\tilde{\gamma}$ must close up. So, each time it passes from R_{k+1} to R_{k-1} it must later pass from R_{k-1} to R_{k+1} .

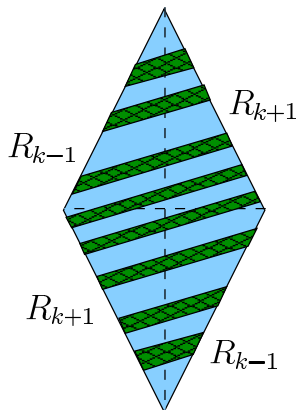
Finding the cylinder (2 of 3)



Claim 2: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ disconnects $MT(\Delta)$.
At least one component contains no singularities with infinite cone angle.

Proof:

Finding the cylinder (2 of 3)

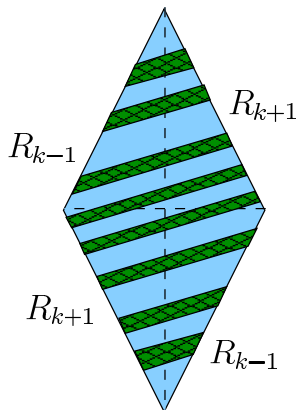


Claim 2: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ disconnects $MT(\Delta)$.
At least one component contains no singularities with infinite cone angle.

Proof:

- By claim 1, each rhombus $R_k \setminus (\tilde{\gamma} \cup \rho(\tilde{\gamma}))$ may be colored so that each infinite cone point is blue, and colors alternate blue/green by adjacency.

Finding the cylinder (2 of 3)



Claim 2: $\tilde{\gamma} \cup \rho(\tilde{\gamma})$ disconnects $MT(\Delta)$.
At least one component contains no singularities with infinite cone angle.

Proof:

- By claim 1, each rhombus $R_k \setminus (\tilde{\gamma} \cup \rho(\tilde{\gamma}))$ may be colored so that each infinite cone point is blue, and colors alternate blue/green by adjacency.
- The colorings of each rhombus agree along the boundaries of the rhombi. So, the green and blue components are distinct.

□

Finding the cylinder (3 of 3)

- The only oriented Euclidean surface with one or two geodesic boundary components is a cylinder.

Finding the cylinder (3 of 3)

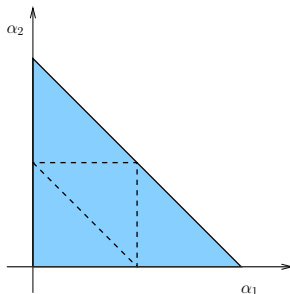
- The only oriented Euclidean surface with one or two geodesic boundary components is a cylinder.
- We still must show that the cylinder contains two centers of rhombi.

Finding the cylinder (3 of 3)

- The only oriented Euclidean surface with one or two geodesic boundary components is a cylinder.
- We still must show that the cylinder contains two centers of rhombi.
- By construction, the rotation by π must preserve the cylinder. A rotation by π of a cylinder has 2 fixed points. The only fixed points of the rotation by π of $MT(\Delta)$ are the centers. \square

The generalization

- The right triangles consist of three lines ℓ_1 , ℓ_2 , and ℓ_3 in the space of triangles \mathcal{T} .

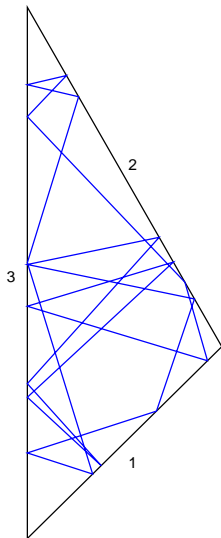


Theorem (H)

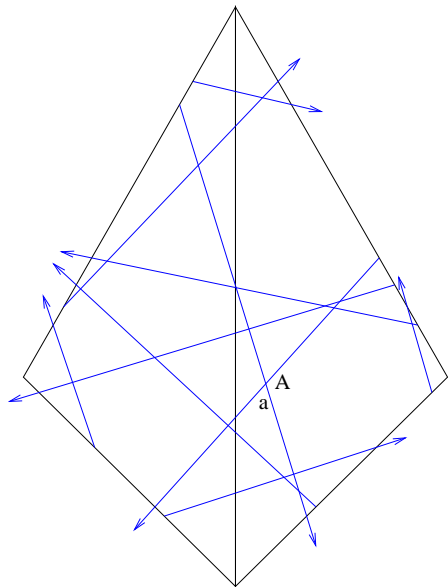
If $\hat{\gamma}$ is a **stable** periodic billiard path in a triangle, then $\text{tile}(\hat{\gamma})$ is contained in one of the four components of $\mathcal{T} \setminus (\ell_1 \cup \ell_2 \cup \ell_3)$.

The argument in action (1 of 5)

- Here is a **stable** periodic billiard path in a slightly obtuse triangle.
- Let's prove that a periodic billiard path with the same orbit type can not appear in a triangle where this obtuse angle becomes right or acute.

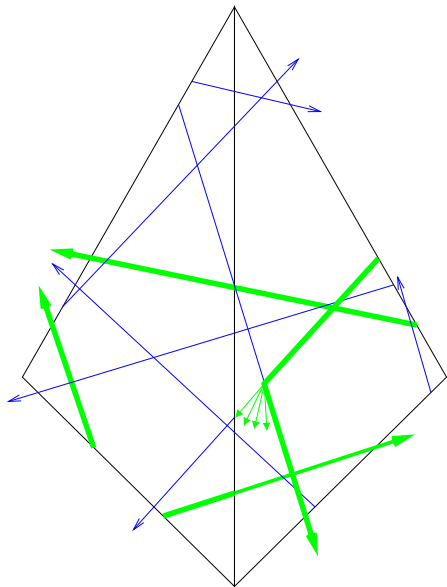


The argument in action (2 of 5)



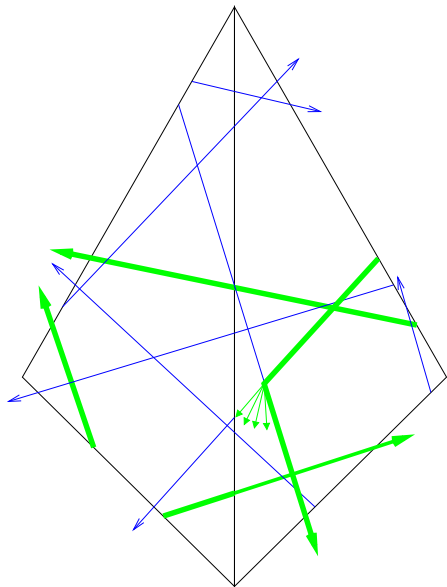
- The proof follows from the “general principle” that intersections between geodesics on locally Euclidean surfaces are “essential.”

The argument in action (3 of 5)



- This angle a must satisfy $0 < a < \pi$.

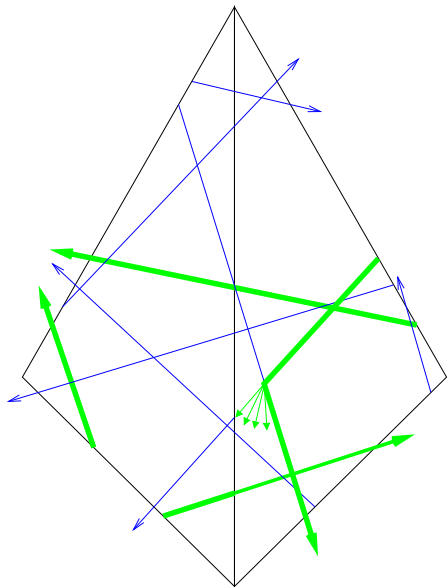
The argument in action (3 of 5)



- This angle a must satisfy $0 < a < \pi$.
- We compute this angle using a "detecting curve" η' on the unit tangent bundle.

$$a = \int_{\eta'} d\theta$$

The argument in action (3 of 5)



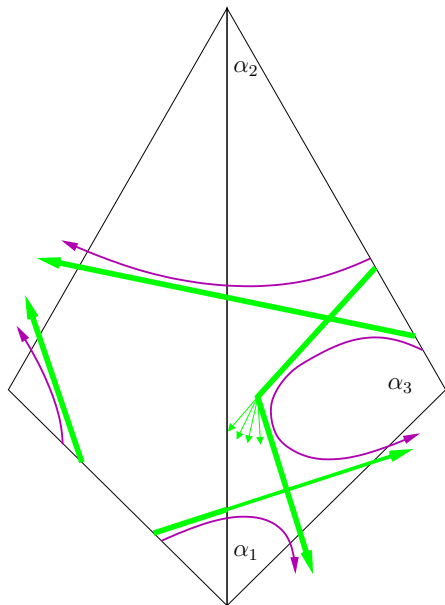
- This angle a must satisfy $0 < a < \pi$.
- We compute this angle using a "detecting curve" η' on the unit tangent bundle.

$$a = \int_{\eta'} d\theta$$

- Thus, for all $\Delta \in \text{tile}(\hat{\gamma})$,

$$0 < \int_{\eta'} d\theta_{\Delta} < \pi$$

The argument in action (4 of 5)



- We compute

$$\begin{aligned} a &= \int_{\eta} d\theta \\ &= 2\alpha_3 - 2\alpha_1 - 2\alpha_2 \\ &= 4\alpha_3 - 2\pi \end{aligned}$$

- For all $\Delta \in \text{tile}(\hat{\gamma})$,

$$0 < a < \pi$$

So,

$$\frac{\pi}{2} < \alpha_3 < \frac{3\pi}{4}$$

The argument in action (5 of 5)

Iterating over all intersections gives a convex bounding box for the tile.

