

TRUCHET TILINGS AND RENORMALIZATION

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ABSTRACT. The Truchet tiles are a pair of square tiles decorated by arcs. When the tiles are pieced together to form a Truchet tiling, these arcs join to form a family of simple curves in the plane. We consider a family of probability measures on the space of Truchet tilings. Renormalization methods are used to investigate the probability that a curve in a Truchet tiling is closed.

1. PRELIMINARY REMARKS

This article was written before I was aware of the connection to the corner percolation model studied by Gábor Pete [Pet08]. The main result in this paper duplicates results in that paper, albeit by completely different methods. The author believes that the approach in this paper can be used to obtain stronger results than indicated in this paper, such as stronger information of the probability of a curve to have length L for any constant L . I hope to soon release a new version addressing this point of view.

The point of view of this paper also connects to rectangle exchange maps. This connection is developed in [Hoo12].

2. INTRODUCTION

The *Truchet tiles* are the two 1×1 squares decorated by arcs as below.



We call the left tile T_{-1} and the right tile T_1 . The subscripts were chosen to indicate the slope of segments formed by straightening the arcs to segments.

Given a function $\tau : \mathbb{Z}^2 \rightarrow \{\pm 1\}$, the *Truchet tiling determined by τ* is the tiling of the plane formed by placing a copy of the tile $T_{\tau(m,n)}$ centered at the point (m,n) for each $(m,n) \in \mathbb{Z}^2$. We denote this tiling by $[\tau]$. Variations of these tilings were first studied for aesthetic reasons by Sébastien Truchet in the early 1700s [Tru04], and this version of tiles were first described by Smith and Boucher [SB87].

The arcs on the tiles of a Truchet tiling join to form a disjoint collection of simple curves in the plane. See Figure 1. We call these the *curves* of the tiling. Each curve is either closed or bi-infinite. A natural question to ask is “how prevalent are the closed curves?” This was asked by Pickover for Truchet tilings which are random in the sense that for each $m,n \in \mathbb{Z}$, $\tau(m,n)$ is determined by the flip of a fair coin [Pic89].

In this paper, we consider Truchet tilings that arise from functions $\tau_{\omega,\omega'} : \mathbb{Z}^2 \rightarrow \{\pm 1\}$ defined in terms of two functions $\mathbb{Z} \rightarrow \{\pm 1\}$, $n \mapsto \omega_n$ and $n \mapsto \omega'_n$. These are the Truchet

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tilings determined by the function

$$(1) \quad \tau_{\omega, \omega'}(m, n) = \omega_m \omega'_n.$$

An example of a portion of such a tiling is shown in Figure 1. We will analyze these tilings with techniques coming from the theory dynamical systems. We will show that closed curves are highly prevalent in some families of tilings, while not so prevalent in other families. For the tilings of the form $[\tau_{\omega, \omega'}]$, we will show that these tilings are renormalizable in the sense of dynamical systems. Renormalization powers the strongest results in this paper. We explain the motivating connections to dynamical systems in the Motivation Section below.

To make the notion of prevalence rigorous, observe that ω and ω' are naturally elements of the full two-sided shift on the alphabet $\{\pm 1\}$, denoted $\Omega_{\pm} = \mathbb{Z}^{\{\pm 1\}}$. The *shift map* $\sigma : \Omega_{\pm} \rightarrow \Omega_{\pm}$ is defined by $(\sigma(\omega))_n = \omega_{n+1}$. We may think of choosing our ω and ω' at random according to some shift-invariant probability measures μ and μ' on Ω_{\pm} . We then choose an edge e of the tiling by squares centered at the integer points (e.g., take e to join $(-\frac{1}{2}, \frac{1}{2})$ to $(\frac{1}{2}, \frac{1}{2})$). We ask “what is $\mu \times \mu'(A)$ where A is the collection of $(\omega, \omega') \in \Omega_{\pm}$ where the curve through e of the tiling $[\tau_{\omega, \omega'}]$ is closed?” A simple argument shows that shift invariance of μ and μ' guarantees that this number is independent of the choice of e .

In general, we have the following result, which often prevents the tilings with a closed curve through e from being full measure.

Theorem 1 (Drift Theorem). *Suppose μ and μ' are shift-invariant probability measures on Ω_{\pm} satisfying*

$$p = \int_{\Omega_{\pm}} \omega_0 d\mu(\omega) \quad \text{and} \quad q = \int_{\Omega_{\pm}} \omega'_0 d\mu'(\omega').$$

Then the $\mu \times \mu'$ measure of the set of pairs (ω, ω') such that the curve of $[\tau_{\omega, \omega'}]$ through edge e is bi-infinite is at least $\max\{|p|, |q|\}$.

The above result is independent from our renormalization arguments. We prove it and state a stronger version of the result in section 4.4.

The main case of interest for this paper is when the measures μ and μ' are the stationary (shift-invariant) measures associated to some Markov chain with the state space $\{\pm 1\}$. The above theorem indicates that for such measures, the probability that the curve through e is closed is less than one whenever 1 and -1 occur with different probabilities. But, there is a one-parameter family of stationary measures associated to Markov chains with the property that 1 and -1 occur with equal probability. The following theorem addresses these cases.

Fix real constants p and p' with $0 < p, p' < 1$. We describe a method of randomly choosing ω and ω' . Choose $\omega_0, \omega'_0 \in \{\pm 1\}$ randomly according to the flip of a fair coin. Define the remaining values according to the rule that for all integers $n \geq 0$, $\omega_{n+1} = \omega_n$ with probability p and $\omega_{-n-1} = \omega_{-n}$ with probability p . Do the same for ω' with probability p' .

Theorem 2. *Let e be an edge of the square tiling of the plane as above. Fix p and p' , and define ω and ω' randomly as above. With probability 1, the curve through e of $[\tau_{\omega, \omega'}]$ is closed.*

The above theorem is proven with the renormalization techniques mentioned above. Much of this technique applies in general to pairs of shift-invariant measures μ and μ' .

We will informally explain how this notion of renormalization works. Fix $\omega, \omega' \in \Omega_{\pm}$ and consider the tiling $[\tau_{\omega, \omega'}]$ described by Equation 1. Generally, there is a collection of rows and columns of the tiling following statements hold, letting Y be the union of all rows and

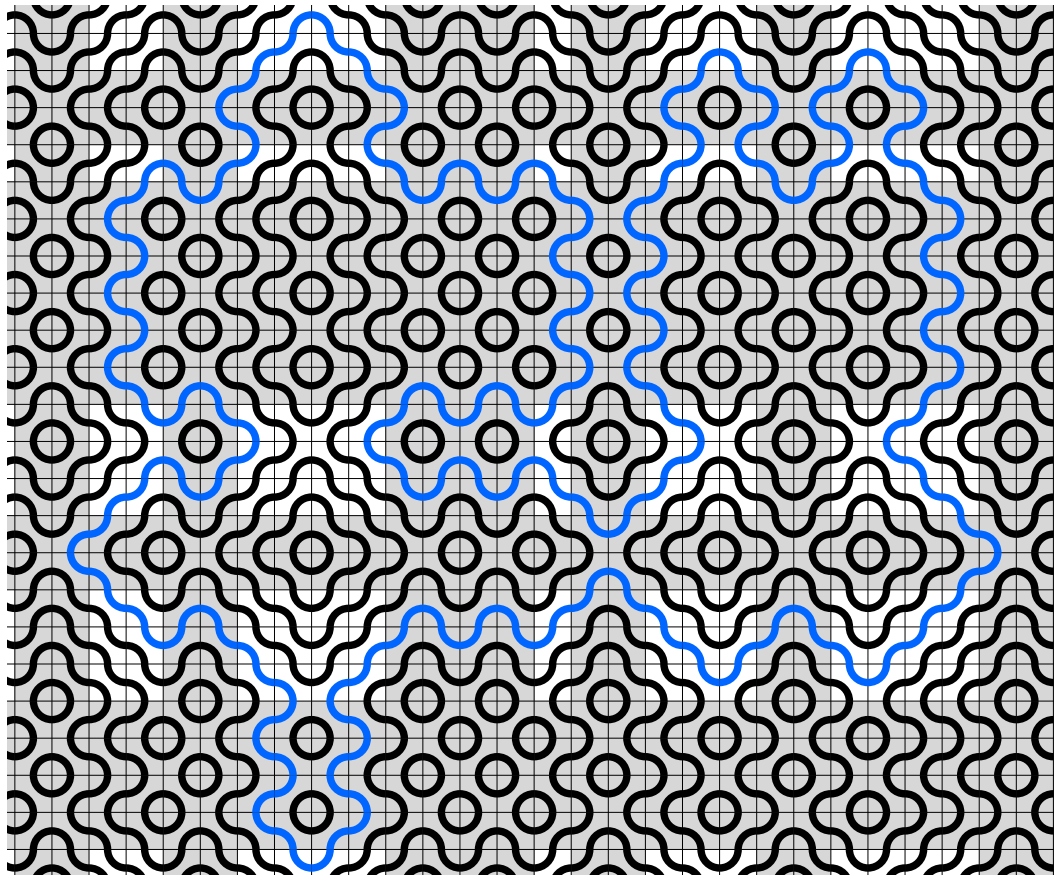


FIGURE 1. A single curve has been highlighted in a tiling determined from ω and ω' chosen at random as described above Theorem 2 for some p and p' .

columns contained in the collection. (An example of Y consists of the union of gray squares in figure 1.)

- (1) A curve of the tiling is contained entirely in Y if and only if the curve closes up after visiting only four squares.
- (2) All other curves of the tiling intersect both Y and its complement.
- (3) When a curve enters Y from the left (respectively, the right) through a vertical edge e in ∂Y , it exits through the nearest vertical edge in ∂Y directly to the right (resp. the left) of e .
- (4) When a curve enters Y from below (resp. above) through a horizontal edge e in ∂Y , it exits through the nearest horizontal edge in ∂Y directly above (resp. below) e .

Assuming these statements, we can then form a new tiling by collapsing all the columns contained in Y , identifying the pairs of edges mentioned in statement (3). Then we collapse the rows in Y , identifying the pairs of edges mentioned in statement (4) in a similar manner. So from $[\tau_{\omega, \omega'}]$ we have obtained a new Truchet tiling, say $[\tau_{\eta, \eta'}]$. Now let γ be a curve in the tiling $[\tau_{\omega, \omega'}]$ which intersects both Y and its complement. Consider the collection of arcs of γ which are contained in the complement of Y . Because of statements (3) and (4), the collapsing process takes these arcs and reassembles them to make a new connected curve γ' in the tiling $[\tau_{\eta, \eta'}]$. The first two statements imply that we have removed all loops of length

4, and reduced the length of all closed loops. So, a loop is closed if and only if it vanishes under some finite number of applications of this collapsing process.

Under certain natural assumptions on ω and ω' , the resulting tiling is determined by another pair $\eta = c(\omega) \in \Omega_{\pm}$ and $\eta' = c(\omega') \in \Omega_{\pm}$. This map c is well defined on some Borel subset $C \subset \Omega_{\pm}$, and we call $c : C \rightarrow \Omega_{\pm}$ the *collapsing map*. The collapsing map acts on shift invariant probability measures μ via $\mu \mapsto \frac{1}{\mu(C)}\mu \circ c^{-1}$.

We can immediately observe for instance that μ -a.e. curve is closed (in the sense of the above theorems), if and only if $\mu \circ c^{-1}$ -a.e. curve is closed. Typically much more than this is true. We define $\omega^{\text{alt}} \in \Omega_{\pm}$ by $\omega_n^{\text{alt}} = (-1)^n$. Assuming that for all integers $n > 0$, the measures $\mu \circ c^{-n}$ and $\mu' \circ c^{-n}$ never has an atom at ω^{alt} , there is a limiting formula for the probability that a curve is closed in terms of the measures $\mu \circ c^{-n}$ and $\mu' \circ c^{-n}$ and the behavior of a cocycle acting on a function space. (See Corollary 24.) In the case of the stationary measures associated to a Markov chain as implicitly discussed in Theorem 2, the action of this cocycle leaves invariant a finite dimensional subspace. Understanding the action of this cocycle restricted to this subspace allows us to prove this Theorem 2.

2.1. Motivation. The original motivation for studying Truchet tilings here arose from connections between Truchet tilings and certain low complexity dynamical systems, such as interval exchange maps and polygon exchange maps. In the paper [?], the connection between Truchet tilings and a family of polygon exchange maps will be discussed in depth. We will briefly explain this connection here because it motivated this work.

A *polygon exchange map* is a map $X \rightarrow X$, where X is a union of polygons, which is piecewise continuous on polygonal pieces, acts as a translation on each piece, and has an image of full area in X . (There may be some ambiguity of definition on the boundaries of the pieces.)

For a more specific example, let F be a finite set, and consider the product $X = \mathbb{T}^2 \times F$ which consists of $\#F$ copies of \mathbb{T}^2 . A polygon exchange map on X , $T : X \rightarrow X$, is a decomposition of X into polygonal pieces $P_1, \dots, P_n \subset X$, a choice of elements $\mathbf{v}_1, \dots, \mathbf{v}_n \in \mathbb{T}^2$ and a choice of elements $c_1, \dots, c_n \in F$ so that the image of the map

$$T(\mathbf{x}, a) = (\mathbf{x} + \mathbf{v}_i, c_i) \text{ whenever } (\mathbf{x}, a) \in P_i$$

has full area. We define the subgroup $G = \langle \mathbf{v}_1, \dots, \mathbf{v}_n \rangle \subset \mathbb{T}^2$. Fixing a $\mathbf{y} \in \mathbb{T}^2$ and an $a \in F$, observe that the orbit of a point (\mathbf{y}, a) is contained in the set $(\mathbf{y} + G) \times F$. Given any $\mathbf{y} \in \mathbb{T}^2$, we define an embedding $\epsilon_{\mathbf{y}} : G \times F \rightarrow X$ via $(\mathbf{g}, a) \mapsto (\mathbf{y} + \mathbf{g}, a)$. For generic \mathbf{y} , we can pull back the action of T to an action on $G \times F$. We define $\Psi_{\mathbf{y}} : G \times F \rightarrow G \times F$ by $\Psi = \epsilon_{\mathbf{y}}^{-1} \circ T \circ \epsilon_{\mathbf{y}}$. The *arithmetic graph* associated to T and \mathbf{y} , $\Gamma(T, \mathbf{y})$ is the graph whose vertices are the points in $G \times F$, and for which an edge is drawn between (\mathbf{g}, a) and $\Psi(\mathbf{g}, a)$ for all $(\mathbf{g}, a) \in G \times F$. Note that the curve of the arithmetic graph through (\mathbf{g}, a) represents the orbit of the point $(\mathbf{y} + \mathbf{g}, a)$ under T . So for instance, the point $(\mathbf{y} + \mathbf{g}, a)$ is periodic if and only if the curve passing through (\mathbf{g}, a) in $\Gamma(T, \mathbf{y})$ is closed.

The arithmetic graph and similar constructions have been a useful tool for proving results about low complexity dynamical systems which require a detailed understanding orbits. For instance, in [PLV08, Proposition 13] it is shown that the analog of an arithmetic graph for a certain interval exchange consists of only finitely many curves. In [Sch07] Schwartz coined the term arithmetic graph, and used the arithmetic graph to resolve a long-standing question of Neumann, “are there outer billiards systems which have unbounded orbits?” In later work, Schwartz showed that a certain first return maps of outer billiards in polygonal

kites is related to polyhedral exchanges by a dynamical compactification construction [Sch09, The Master Picture Theorem]. This construction relates the arithmetic graph used in outer billiards with the arithmetic graph of a polygon exchange mentioned above. The arithmetic graph also played a primary role in [Sch10].

A powerful tool for understanding the dynamical systems mentioned above has been renormalization. For a polygon exchange map $T : X \rightarrow X$, for instance, we can construct a new polygon exchange map by considering the return map to a polygon or union of polygons. Repeatedly applying this trick can be useful for proving results about the long term behavior of the system. This is commonly used to answer ergodic theoretic questions about interval exchange maps [MT02]. For a specific polygon exchange map, renormalization has been used to show that the set of points with periodic orbits have full measure [AKT01]. This is similar to our goals here.

This paper came out of an attempt find a simple example where renormalization can be understood in terms of the arithmetic graph. The polygon exchange maps appearing in [Sch09] appear complicated, but the associated arithmetic graphs have many nice properties. For instance, the connected components of these arithmetic graphs form a collection of simple curves. Truchet tilings represent a ways to force this behavior independent of constructions involving outer billiards. Moreover, we can obtain many Truchet tilings as instances of arithmetic graphs of polygon exchange maps [?]. In these cases, the renormalization of tilings described in the introduction corresponds to a renormalization (first return map) of the associated polygon exchange map. This paper came out of the realization that, in this particular case, by understanding the action of renormalization on the arithmetic graph, we can generalize the renormalization of a family of polygon exchange maps to a renormalization scheme applicable to a more general class of dynamical systems. These are the systems described in Section 4.

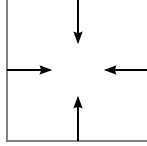
Finally, it should be noted that the original motivation for studying Truchet Tilings by Truchet [Tru04] and Smith [Tru04] was aesthetic. These motivations continue today. See for instance, [LR06], and [Bro08]. More general families of curves associated to tilings have been considered. For instance, [OC99] considers similar curves in Penrose tilings.

Aside from the above motivations, Truchet tilings have also played role in understanding a variant of the cellular automata known as Langton's Ant [GPST95].

2.2. Outline. In Section 3, we explain how to think of the space of Truchet tilings as a dynamical system. In Section 4, we restrict attention to the case of tilings determined by a pair of elements of the shift space Ω_{\pm} as in Equation 1. We also provide the necessary background on shift spaces and shift invariant measures here. In Section 4.4, we prove the Drift Theorem and a stronger variant. Section 5 states and proves the renormalization results which apply to many pairs of shift-invariant measures. This culminates in Section 5.3, which explains the renormalization process and constructs the cocycle alluded to in the introduction. Finally, Section 6 develops these renormalization theorems in the context of the measures relevant to Theorem 2. Section 6.3 does the necessary calculation to prove this theorem.

3. DYNAMICS ON TRUCHET TILINGS

Consider the unit square centered at the origin with horizontal and vertical sides. An *inward normal* to the square is a unit vector which is based at a midpoint of an edge and is pointed into the square. See below



We do not keep track of the location at which the normal is placed, so the four inward normals are just the vectors $(1, 0)$, $(0, 1)$, $(-1, 0)$ and $(0, -1)$. We use N to denote the collection of inward normals.

Let \mathcal{T} be the collection of maps $\mathbb{Z}^2 \rightarrow \{\pm 1\}$. We will define a dynamical system on $\mathcal{T} \times N$. Choose $(\tau, \mathbf{v}) \in \mathcal{T} \times N$. The inward normal $\mathbf{v} \in N$ is a vector based at a midpoint of the square at the origin pointed inward. The Truchet tiling $[\tau]$ determined by τ places the tile $T_{\tau(0,0)}$ at the origin. We drag the vector inward along an arc of this tile keeping the vector tangent to the arc. After a quarter turn, we end up as a vector pointed out of the square centered at the origin. So, the vector points into a square adjacent to the square at the origin. We translate the whole tiling so that this new square becomes centered at the origin.

Formally, this is the dynamical system $\Phi_0 : \mathcal{T} \times N \rightarrow \mathcal{T} \times N$ given by

$$(2) \quad \Phi_0(\tau, (a, b)) = (\tau \circ S_{s(b,a)}, s(b, a)),$$

where $s = \tau(0, 0) \in \{\pm 1\}$ and $S_{s(b,a)}$ is the translation of the plane by the vector $s(b, a)$.

4. TRUCHET TILING SPACES FROM SHIFT SPACES

In this paper we will concentrate on Truchet tilings which arise from a pair of bi-infinite sequences of elements of the set $\{\pm 1\}$. As in the introduction, we will use notation from the world of shift spaces to denote these bi-infinite sequences. Namely, an element $\omega \in \Omega_{\pm}$ is a bi-infinite sequence of elements of $\{\pm 1\}$. For $n \in \mathbb{Z}$, we use ω_n to denote the n -th element of the sequence ω .

Given $\omega, \omega' \in \Omega_{\pm}$, we obtain a function $\tau_{\omega, \omega'} : \mathbb{Z}^2 \rightarrow \{\pm 1\}$ as in equation 1 of the introduction. In this paper, we will be interested in studying the dynamics of Φ_0 on the collection of all $\tau_{\omega, \omega'}$. This collection of tilings is Φ_0 -invariant and admits a natural renormalization procedure as we explain in section 5. In this section, we reveal some of the more basic structure of the map Φ_0 restricted to these types of tilings.

4.1. Background on shift spaces. We briefly recall some basic facts about two-sided shift spaces here. For further background see [LM95], for instance.

Let \mathcal{A} be a finite set called an *alphabet*. The set $\mathcal{A}^{\mathbb{Z}}$ is called the *full (two-sided) shift* on \mathcal{A} .

For integers $m < n$, let $f : \{m, m+1, \dots, n\} \rightarrow \mathcal{A}$ be an arbitrary function. The *cylinder set* determined by f is the set

$$(3) \quad \mathcal{C}(f) = \{\omega \in \mathcal{A}^{\mathbb{Z}} : \omega_i = f(i) \text{ for all } i = m, \dots, n.\}$$

We equip $\mathcal{A}^{\mathbb{Z}}$ with the topology generated by the cylinder sets. This is the coarsest topology which makes each cylinder set open. Observe that the cylinder sets are also closed. An equivalent description of this topology is obtained by considering elements of $\mathcal{A}^{\mathbb{Z}}$ as functions $\mathbb{Z} \rightarrow \mathcal{A}$. From this point of view, this is the topology of pointwise convergence on compact subsets of \mathbb{Z} , where \mathcal{A} is given the discrete topology. With this topology, the set $\mathcal{A}^{\mathbb{Z}}$ is homeomorphic to a Cantor set.

The *shift map* $\sigma : \mathcal{A}^{\mathbb{Z}} \rightarrow \mathcal{A}^{\mathbb{Z}}$ is the homeomorphism of the full shift space defined by

$$(4) \quad [\sigma(\omega)]_n = \omega_{n+1}.$$

A *shift space* Ω is a closed, shift-invariant subset of a full shift space. We endow Ω with the subspace topology.

A *shift-invariant measure* on a shift space Ω is a Borel measure μ satisfying

$$\mu \circ \sigma^{-1}(A) = \mu(A) \quad \text{for all Borel subsets } A \subset \Omega.$$

Full shift spaces admit a plethora of shift-invariant probability measures.

4.2. Tiling spaces from shift spaces. As before, we let $\Omega_{\pm} = \{\pm 1\}^{\mathbb{Z}}$ denote the full shift space on the alphabet $\{\pm 1\}$. Given a pair of elements $\omega, \omega' \in \Omega_{\pm}$, we obtain a map $\tau_{\omega, \omega'} : \mathbb{Z}^2 \rightarrow \{\pm 1\}$ as in equation 1. This function in turn determines a tiling $[\tau_{\omega, \omega'}]$ as described in the introduction. Note that the map $(\omega, \omega') \rightarrow \tau_{\omega, \omega'}$ is two-to-one, with $\tau_{\omega, \omega'} = \tau_{-\omega, -\omega'}$, where $-\omega$ denotes the element of Ω_{\pm} given by $(-\omega)_n = -\omega_n$.

The collection $\{\tau_{\omega, \omega'} : \omega, \omega' \in \Omega_{\pm}\}$ is easily seen to be translation invariant, and therefore the set $\{\tau_{\omega, \omega'} : \omega, \omega' \in \Omega_{\pm}\} \times N$ is invariant under Φ_0 . There is a natural lift of the action of Φ_0 on this set to an action on the set $X = \Omega_{\pm} \times \Omega_{\pm} \times N$ given by

$$(5) \quad \Phi(\omega, \omega', (a, b)) = (\sigma^{sb}(\omega), \sigma^{sa}(\omega'), s(b, a)),$$

with $s = \omega_0 \omega'_0$. (Here, σ^{-1} denotes the inverse of the shift map defined by $(\sigma^{-1}(\omega))_n = \omega_{n-1}$.) We call Φ a lift of Φ_0 because if $\Phi(\omega, \omega', \mathbf{v}) = (\eta, \eta', \mathbf{v}')$ then $\Phi_0(\tau_{\omega, \omega'}, \mathbf{v}) = (\tau_{\eta, \eta'}, \mathbf{v}')$. Observe that the inverse of Φ is given by

$$(6) \quad \Phi^{-1}(\omega, \omega', (a, b)) = (\sigma^{-a}(\omega), \sigma^{-b}(\omega'), \omega_{-a} \omega'_{-b}(b, a)).$$

We now make some preliminary observations about Φ .

Proposition 3. *Let $\Omega, \Omega' \subset \Omega_{\pm}$ be shift spaces. The set $\Omega \times \Omega' \times N$ is a closed Φ -invariant subset of $\Omega_{\pm} \times \Omega_{\pm} \times N$.*

The above proposition trivially follows from the definitions.

Proposition 4. *Suppose μ and μ' are shift invariant probability measures on Ω and Ω' , respectively. Let μ_N be the discrete probability measure on N so that $\mu_N(\{\mathbf{v}\}) = \frac{1}{4}$ for each $\mathbf{v} \in N$. Then $\mu \times \mu' \times \mu_N$ is a Φ -invariant probability measure on $\Omega \times \Omega' \times N$.*

Proof. It is sufficient to show Φ -invariance of $\nu = \mu \times \mu' \times \mu_N$ on sets of the form $A \times B \times \{\mathbf{v}\}$, where $\mathbf{v} \in N$ and $A \subset \Omega$ and $B \subset \Omega'$ are Borel sets chosen so that the product $s = \omega_0 \omega'_0$ is independent of the choice of $\omega \in A$ and $\omega' \in B$. Then by definition of Φ , shift invariance of the measures μ and μ' , and the permutation invariance of μ_N ,

$$\nu \circ \Phi(A \times B \times \{(a, b)\}) = \nu(\sigma^{sb}(A) \times \sigma^{sa}(B) \times \{s(b, a)\}) = \nu(A \times B \times \{(a, b)\}).$$

□

4.3. Periodic orbits. Suppose $(\omega, \omega', \mathbf{v}) \in X$ satisfies $\Phi^n(\omega, \omega', \mathbf{v}) = (\omega, \omega', \mathbf{v})$. We say $(\omega, \omega', \mathbf{v})$ has an *stable periodic orbit of period n* if n is the smallest number for which there are open neighborhoods U and U' of ω and ω' respectively for which each $(\eta, \eta', \mathbf{v}) \in U \times U' \times \{\mathbf{v}\}$ satisfies $\Phi^n(\eta, \eta', \mathbf{v}) = (\eta, \eta', \mathbf{v})$. The following proposition characterizes the points with stable periodic orbits.

Proposition 5 (Stability Proposition). *Let $(\omega, \eta, \mathbf{v}) \in X$, and use $(\omega^k, \eta^k, \mathbf{v}^k)$ to denote $\Phi^k(\omega, \omega', \mathbf{v})$. The following statements hold.*

- (1) *If $(\omega, \omega', \mathbf{v}) \in X$ has a stable periodic orbit of period n , then it is also (least) period- n under Φ in the usual sense.*
- (2) *$(\omega, \omega', \mathbf{v}) \in X$ has a stable periodic orbit if and only if the curve of the tiling $[\tau_{\omega, \omega'}]$ passing through the normal \mathbf{v} to the square centered at the origin is closed. In this case, the period of $(\omega, \omega', \mathbf{v})$ is the number of squares the associated closed curve of the tiling intersects, counting multiplicities.*
- (3) *$(\omega, \omega', \mathbf{v}) \in X$ has a stable periodic orbit of period n if and only if n is the smallest positive integer for which both $\Phi(\omega, \omega', \mathbf{v}) = (\omega, \omega', \mathbf{v})$ and $\sum_{i=0}^{n-1} \mathbf{v}^i = (0, 0)$.*

The multiplicities mentioned in the proposition deal with the fact that curves may (a priori) intersect the same square twice. (In fact, no curve intersects a square twice. This follows from Lemma 8, below.)

Proof. For $n \geq 1$ let $a_n = \sum_{k=1}^n \mathbf{v}_1^k$ and $b_n = \sum_{k=1}^n \mathbf{v}_2^k$. By induction using equation 5, we observe that $\omega^n = \sigma^{a_n}(\omega)$ and $\eta^n = \sigma^{b_n}(\omega')$. Now suppose $(\omega^k, \eta^k, \mathbf{v}^k)$ is period n . Note that (a_n, b_n) equals the vector sum in statement (3). We see $\sigma^{a_n}(\omega) = \omega$ and $\sigma^{b_n}(\omega') = \omega'$. Therefore if $a_n \neq 0$, we see that ω must be period- a_n under the shift map. This is not an open condition, so $(\omega, \omega', \mathbf{v})$ cannot have a stable periodic orbit of period n . This is similarly true if $b \neq 0$. Extending this argument, we observe that $a_{kn} = ka_n$ and $b_{kn} = kb_n$ for integers $k > 1$. Therefore, $(\omega, \omega', \mathbf{v})$ cannot have a stable periodic orbit of any period. Conversely, if both $a_n = 0$ and $b_n = 0$, then we let $a_+ = \max\{a_1, \dots, a_n\}$ and $a_- = \min\{a_1, \dots, a_n\}$. Define b_+ and b_- similarly. Then consider the open sets

$$U = \{\alpha \in \Omega_{\pm} : \alpha_k = \omega_k \text{ for all } k \text{ with } a_- \leq k \leq a_+\}, \text{ and}$$

$$U' = \{\beta \in \Omega_{\pm} : \beta_k = \omega'_k \text{ for all } k \text{ with } b_- \leq k \leq b_+\}.$$

Then observe that for $\alpha \in U$ and $\beta \in U'$ we have $\Phi^n(\alpha, \beta, \mathbf{v}) = (\alpha, \beta, \mathbf{v})$. Therefore, $(\omega, \omega', \mathbf{v}) \in X$ has a stable periodic orbit of period n . Finally, observe that the condition that $a_n = 0$ and $b_n = 0$ is equivalent to the statement that the curve of the tiling $[\tau_{\omega, \omega'}]$ passing through \mathbf{v} is closed. \square

Remark 6. *Not all periodic orbits are stable. When $\omega_n = 1$ and $\omega'_n = 1$ for all $n \in \mathbb{Z}$, we have $\Phi^2(\omega, \omega', \mathbf{v}) = (\omega, \omega', \mathbf{v})$ for all \mathbf{v} , but $(\omega, \omega', \mathbf{v})$ is not an n -stable periodic orbit for any n .*

Corollary 7. *Let μ and μ' be shift-invariant measures on Ω_{\pm} . Let $P_n \subset X$ be the set of all $(\omega, \omega', \mathbf{v})$ with stable periodic orbits of period n . Fix an edge e of the tiling of the plane by squares centered at the integer points as in the theorem of the introduction. Then, $\mu \times \mu' \times \mu_N(P_n)$ is equal to the $\mu \times \mu'$ measure of those (ω, ω') so that the curve of the tiling $[\tau_{\omega, \omega'}]$ through e is closed and visits n squares (counting multiplicities).*

The proof follows from the Stability Proposition together with the observation that both quantities are translation invariant. The fact that the horizontal or vertical orientation of e is irrelevant follows from the fact that curves of the tiling alternate intersecting horizontal and vertical edges. We omit a detailed proof of this corollary.

4.4. An invariant function and drift. In this section, we prove the Drift Theorem. Ideas for this result come from the drift vector of an interval exchange transformation. See [PLV08], for instance.

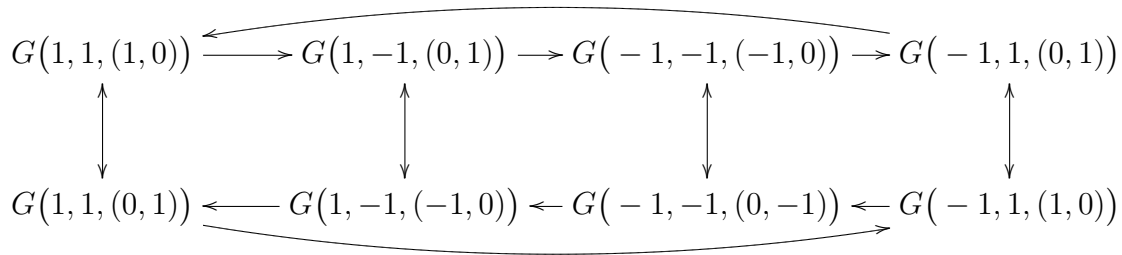
The first observation of this section is that there is a simple Φ invariant function on $X = \Omega \times \Omega' \times N$.

Lemma 8 (Invariant function). *Let $M(\omega, \omega', (a, b)) = b\omega_0 + a\omega'_0$. This is a Φ -invariant function from X to $\{\pm 1\}$.*

Sketch of proof. We partition the space $\Omega_{\pm} \times \Omega_{\pm} \times N$ into 16 subsets $G(s, s', (a, b))$ according to choices of $s, s' \in \{\pm 1\}$ and $(a, b) \in N$. These groups are defined

$$G(s, s', (a, b)) = \{(\omega, \omega', (a, b)) \in \Omega_{\pm} \times \Omega_{\pm} \times N : \omega_0 = s \text{ and } \omega'_0 = s'\}.$$

Write \mathcal{G} for the set of these 16 subsets. Let \sim be the strongest equivalence relation on \mathcal{G} for which $G_1 \sim G_2$ whenever $\Phi(G_1)$ intersects G_2 . The equivalence classes can be computed by drawing the graph where the nodes are elements of \mathcal{G} and the arrows are drawn from G_1 to G_2 whenever $\Phi(G_1)$ intersects G_2 ; the equivalence classes are then the connected components of this graph. One of the two maximal equivalence classes is shown below.



Note that $M \equiv 1$ on this equivalence class. The function M takes the value -1 on the eight remaining subsets. \square

The following is a restatement of the Drift Theorem in the introduction. Equivalence follows from the Corollary 7.

Theorem 9 (Restated Drift Theorem). *Suppose μ and μ' are shift-invariant probability measure on Ω_{\pm} satisfying*

$$p = \int_{\Omega_{\pm}} \omega_0 d\mu(\omega) \quad \text{and} \quad q = \int_{\Omega_{\pm}} \omega'_0 d\mu'(\omega').$$

Then the $\mu \times \mu' \times \mu_N$ measure of the set of all $(\omega, \omega', \mathbf{v})$ without stable periodic orbits is at least $\max\{|p|, |q|\}$.

Proof. Let $X_s = M^{-1}(\{s\})$ for $s \in \{\pm 1\}$. We would like to compute the integral

$$I = \int_{X_s} (a, b) d(\mu \times \mu' \times \mu_N),$$

with the integral taken over all $(\omega, \omega', (a, b)) \in X_s$. Let $X_s(a, b)$ denote those $(\omega, \omega', \mathbf{v}) \in X_s$ with $\mathbf{v} = (a, b)$. Then,

$$I = \frac{1}{4} \sum_{(a,b) \in N} \int_{X_s(a,b)} (a, b) d(\mu \times \mu'),$$

with the integral take over all pairs (ω, ω') with (a, b) fixed by the sum. The $\frac{1}{4}$ appears because of the removal of μ_N . Consider the case $(a, b) = (1, 0)$. Note that $M = (\omega, \omega', (1, 0)) = \omega'_0$, so that for this term

$$\int_{X_s(1,0)} (1, 0) d(\mu \times \mu') = \int_{X_s(1,0)} (s\omega'_0, 0) d(\mu \times \mu') = s(q, 0).$$

Similarly, in the case $(a, b) = (-1, 0)$, we have $M = (\omega, \omega', (-1, 0)) = -\omega'_0$, so again

$$\int_{X_s(-1,0)} (-1, 0) d(\mu \times \mu') = \int_{X_s(s\omega'_0,0)} (-\omega'_0, 0) d(\mu \times \mu') = s(q, 0).$$

Similar analysis holds for the cases $(a, b) = (\pm 1, 1)$ and show that the total integrals is given by $I = \frac{s}{2}(q, p)$.

Let P_s denote the set of all $(\omega, \omega', (a, b)) \in X_s$ which have stable periodic parameters. This set is Φ -invariant, and the proposition above guarantees that

$$\int_{P_s} (a, b) d(\mu \times \mu' \times \mu_N) = 0.$$

Also note that for any $(\omega, \omega', (a, b))$ that if (a', b') is the N component of $\Phi((\omega, \omega', (a, b)))$ then $(a, b) + (a', b')$ is one of the four vectors of the form $(\pm 1, \pm 1)$. Therefore, for any Φ -invariant set $A \subset \Omega_{\pm} \times \Omega_{\pm} \times N$ with

$$\int_A (a, b) d(\mu \times \mu' \times \mu_N) = (x, y)$$

we have $|x| \leq \frac{1}{2}\mu \times \mu' \times \mu_N(A)$ and $|y| \leq \frac{1}{2}\mu \times \mu' \times \mu_N(A)$. Applying this to the invariant set $X_s \setminus P_s$, we see

$$\frac{s}{2}(q, p) = I = \int_{X_s \setminus P_s} (a, b) d(\mu \times \mu' \times \mu_N)$$

so that $\mu \times \mu' \times \mu_N(X_s \setminus P_s) \leq \max\{|p|, |q|\}$, as desired. \square

We get a stronger result using the ergodic decomposition. Let us briefly recall the statement in this context. Let \mathcal{M} denote the collection of shift-invariant probability measures on Ω_{\pm} , and $\mathcal{E} \subset \mathcal{M}$ denote those measures which are ergodic. For any shift invariant probability measure μ , there is unique probability measure λ defined on \mathcal{M} so that $\lambda(\mathcal{E}) = 1$ and for all continuous $f : \Omega_{\pm} \rightarrow \mathbb{R}$ we have

$$\int_{\Omega_{\pm}} f d\mu = \int_{\mathcal{E}} \int_{\Omega_{\pm}} f(x) d\nu(x) d\lambda(\nu).$$

Now let $\chi : X \rightarrow \mathbb{R}$ be the characteristic function on the set of all $(\omega, \omega', \mathbf{v})$ without stable periodic orbits. Let μ be a shift-invariant probability measure as above. And λ be the measure obtained from the ergodic decomposition. Then, applying the Drift Theorem to the ergodic measures yields

$$\begin{aligned} \int_X \chi(x) d(\mu \times \mu' \times \mu_N)(x) &= \int_{\Omega_{\pm}} \int_N \int_{\Omega_{\pm}} \chi(\omega, \omega', \mathbf{v}) d\mu'(\omega') d\mu_N(\mathbf{v}) d\mu(\omega) \\ &= \int_{\mathcal{E}} \int_{\Omega_{\pm}} \int_N \int_{\Omega_{\pm}} \chi(\omega, \omega', \mathbf{v}) d\mu'(\omega') d\mu_N(\mathbf{v}) d\nu(\omega) d\lambda(\nu) \\ &\geq \int_{\mathcal{E}} \left| \int_{\Omega_{\pm}} \omega_0 d\nu(\omega) \right| d\lambda(\nu). \end{aligned}$$

The following is what is weaker than the above argument gives.

Corollary 10. *Let λ and λ' be the measures obtained from the ergodic decomposition applied to μ and μ' , respectively. If the $\mu \times \mu' \times \mu_N$ measure of the set of all $(\omega, \omega', \mathbf{v})$ without stable periodic orbits is zero, then for λ -a.e. (and λ' -a.e.) $\nu \in \mathcal{E}$ we have $\int_{\Omega_{\pm}} \omega_0 d\nu(\omega) = 0$.*

5. RENORMALIZATION OF TRUCHET TILINGS

In this section, we will describe the renormalization procedure for the dynamical system $\Phi : X \rightarrow X$. Informally, this procedure can be described in terms of tilings as in the introduction. Given a tiling $[\tau_{\omega, \omega'}]$, we renormalize to obtain a new tiling $[\tau_{\eta, \eta'}]$ with $\eta = c(\omega)$ and $\eta' = c(\omega')$. The function c is called a collapsing map and is defined in Subsection 5.2. The renormalized tiling is obtained from the original by collapsing some rows and columns of tiles to lines. This is explained in the following subsection.

5.1. Notation for words. A *word* in $\{\pm 1\}$ is an element w of a set $\{\pm 1\}^{\{1, \dots, n\}}$ for some $n = \ell(w) \geq 0$, called the *length* of w . We use \mathcal{W} to denote the collection of all words. We write $w = w_1 \dots w_n$ with $w_i \in \{\pm 1\}$ to denote a word, and \emptyset to denote the unique word of length 0. To simplify notation of the elements in $\{\pm 1\}$, we use $+$ to denote 1 and $-$ to denote -1 . So the word w where $w_1 = 1$ and $w_2 = -1$ can be simply written as $w = +-.$

Adjacency indicates the *concatenation* of words; if $w, w' \in \mathcal{W}$ then

$$ww' = w_1 \dots w_{\ell(w)} w'_1 \dots w'_{\ell(w')}.$$

For an integer $n \geq 0$, the expression w^n indicates the n -fold concatenation $ww \dots w$, with w appearing n times.

If $a \leq b \leq c$ and $w = w_a \dots w_c$ with $w_i \in \{\pm 1\}$, then we can consider the function $f : \{a - b, \dots, c - b\} \rightarrow \{\pm 1\}$ given by $f(i - b) = w_i$. By equation 3, this determines a cylinder set $\mathcal{C}(f)$, which we also denote by $\mathcal{C}(w_a \dots \widehat{w}_b \dots w_c)$, with the hat indicating that w_b represents the value of the zeroth entry of the words in the cylinder set.

5.2. The collapsing map on shift spaces. The idea of the collapsing function c mentioned at the beginning of this section is to removed any substrings of the form $-+$ and then slide the remaining entries together. For example,

$$c(\dots \underline{-+} + - - \underline{-+} \underline{-+} \widehat{+} - \underline{-+} + + \dots) = \dots + - - \widehat{+} - + + \dots,$$

where underlined entries have been removed. There are two potential reasons why $c(\omega)$ may not be well defined. First, the zeroth entry might be removed by this process. Second, the remaining list may not be bi-infinite.

Formally, we define $S \subset \Omega_{\pm}$ to be the union of two cylinder sets $S = \mathcal{C}(\widehat{-+}) \cup \mathcal{C}(-\widehat{+})$. Given $\omega \in \Omega_{\pm}$, we set $K(\omega) \subset \mathbb{Z}$ to be

$$(7) \quad K(\omega) = \{k \in \mathbb{Z} : \sigma^k(\omega) \notin S\}.$$

We say that $\omega \in \Omega_{\pm}$ is *unbounded-collapsible* if $K(\omega)$ is unbounded in both directions, *zero-collapsible* if $0 \in K(\omega)$, and *collapsible* if it is both unbounded- and zero-collapsible. We use C to denote the collection of collapsible elements of Ω_{\pm} . If $\omega \in C$, then there is a unique order preserving indexing $\mathbb{Z} \rightarrow K(\omega)$ denoted $i \mapsto k_i$ so that $K(\omega) = \{k_i : i \in \mathbb{Z}\}$ and $k_0 = 0$. We use $c(\omega) \in \Omega_{\pm}$ to denote the *collapse* of ω , which we define by $c(\omega)_i = \omega_{k_i}$. So, the *collapsing map* is a map $c : C \rightarrow \Omega_{\pm}$.

In the remainder of this subsection, we investigate properties of this map.

Proposition 11. *The collapsing map is surjective.*

To prove this proposition, we explicitly construct the inverse images. For this, we define a process we call insertion. An insertion rule is determined by a function $f : \mathbb{Z} \rightarrow \mathcal{W}$. Let $\omega \in \Omega_{\pm}$. From f , we determine a strictly increasing bi-infinite sequence of integers $\langle m_i \rangle_{i \in \mathbb{Z}}$ inductively according to the following two rules.

- $m_0 = 0$.
- For all $i \in \mathbb{Z}$, then $m_{i+1} - m_i = 1 + \ell \circ f(i)$.

The *insertion function determined by f* , $\mathcal{I}_f : \Omega^{\pm} \rightarrow \Omega^{\pm}$ evaluated at η is given by the following rules.

- $\mathcal{I}_f(\eta)_k = \eta_i$ if $k = m_i$ for some $i \in \mathbb{Z}$.
- $\mathcal{I}_f(\eta)_k = f(i)_{k-m_i}$ if $m_i < k < m_{i+1}$ for some $i \in \mathbb{Z}$.

Proposition 12. *Let $\mathcal{W}_{-+} = \{(-+)^n : n \geq 0\}$. For all $\eta \in \Omega_{\pm}$, we have*

$$c^{-1}(\eta) = \{\mathcal{I}_f(\eta) : f(i) \in \mathcal{W}_{-+} \text{ for all } i \text{ and } f(i) \neq \emptyset \text{ whenever } \eta_i = -1 \text{ and } \eta_{i+1} = 1\}.$$

Proof. Suppose $c(\omega) = \eta$. We will show that ω is an element of the set on the right hand side of the equation. Consider the set $K(\omega)$ indexed by $i \mapsto k_i$ as in the definition of the collapsing map. By definition of c , for all i we have $\eta_{k_i} = \omega_i$, and $\eta_{k_{i+1}} \dots \eta_{k_{i+1}-1} \in \mathcal{W}_{-+}$. This proves that $\eta = \mathcal{I}_f(\omega)$ with $f(i) \in \mathcal{W}_{-+}$ for all i . Finally, by definition of $K(\eta)$, when $k_{i+1} = k_i + 1$ we must have $k_i \neq -1$ or $k_{i+1} \neq 1$. This is equivalent to the statement that $f(i) \neq \emptyset$ whenever $\omega_i = -1$ and $\omega_{i+1} = 1$.

Conversely, suppose $\omega = \mathcal{I}_f(\eta)$ with f as above. Define $K(\omega)$. Also define m_i as in the definition of insertion function applied to η . Let $M = \{m_i : i \in \mathbb{Z}\}$. We will show that $M = K(\omega)$. Then it follows from the definitions of c and \mathcal{I}_f that $c(\omega) = \eta$ as desired. It is clearly true that $M \subset K(\eta)$, because every inserted word is of the form $(-+)^n$ for some $n \geq 0$. Now we show that $K(\omega) \subset M$. Suppose $k \in K(\omega) \setminus M$. Since $k \notin M$, we note that $m_i < k < m_{i+1}$ for some $i \in \mathbb{Z}$. Therefore by the definition of insertion function and the fact we only insert words in \mathcal{W}_{-+} , we have that the word

$$\omega_{m_{i+1}} \omega_{m_i+2} \dots \omega_{m_{i+1}-1} = (-+)^n.$$

for $n = \frac{m_{i+1} - m_i - 1}{2} > 0$. Observe by definition of $K(\omega)$ that $\{m_i + 1, m_i + 2, \dots, m_{i+1} - 1\} \not\subset K(\omega)$ and therefore $k \notin K(\omega)$, which is a contradiction. \square

Suppose $a, b \in \mathbb{Z}$ with $a \leq 0 \leq b$ and $w_a, \dots, w_b \in \{\pm 1\}$. Recall, we use $\mathcal{C}(w_a \dots \widehat{w_0} \dots w_b)$ to denote the cylinder set consisting of those ω for which $\omega_k = w_k$ for all k satisfying $a \leq k \leq b$.

Corollary 13 (Preimages of cylinder sets). *Let C_u denote the set of unbounded collapsible elements of Ω_{\pm} . Suppose $a \leq 0 \leq b$ and $w_a, \dots, w_b \in \{\pm 1\}$. Then $c^{-1}(\mathcal{C}(w_a \dots \widehat{w_0} \dots w_b))$ is given by*

$$C_u \cap \bigcup_{n_a, \dots, n_{b-1}} \mathcal{C}(s_- w_a (-+)^{n_a} w_{a+1} (-+)^{n_{a+1}} \dots \widehat{w_0} \dots (-+)^{n_{b-2}} w_{b-1} (-+)^{n_{b-1}} w_b s_+),$$

where the union is taken over all choices of integers n_k such that $n_k \geq 1$ if $w_k = -1$ and $w_{k+1} = 1$, and $n_k \geq 0$ otherwise. The word $s_- = +$ if $w_a = 1$ and $s_- = \emptyset$ otherwise. The word $s_+ = -$ if $w_b = -1$ and $s_+ = \emptyset$ otherwise.

Corollary 14. *The collapsing map is continuous.*

Proof. By the above corollary, the inverse image of a cylinder set is a union of cylinder sets intersected with C and therefore open in C . Since the cylinder sets form a basis for the topology, the inverse image of any open set is open in C . Therefore, c is continuous. \square

Proposition 15. *If $\Omega \subset \Omega_{\pm}$ is a shift space and the alternating element ω^{alt} defined by $\omega_n^{\text{alt}} = (-1)^n$ is not an element of Ω , then every element of Ω is unbounded-collapsible.*

Proof. Suppose $\omega \in \Omega$ is not unbounded-collapsible. Then, $\omega_{n+1} = -\omega_n$ for all $n > N$ or all $n < N$ for some $N \in \mathbb{Z}$. Therefore, ω^{alt} can be obtained as a limit of shifts of ω . \square

We have the following analog for measures.

Proposition 16. *Suppose μ is a shift-invariant probability measure on Ω_{\pm} , and that*

$$\mu(\{\omega \in \Omega_{\pm} : \omega \text{ is not unbounded-collapsible}\}) > 0.$$

Then $\mu(\{\omega^{\text{alt}}\}) > 0$.

Lemma 17. *Suppose $A \subset \Omega_{\pm}$ is shift-invariant, then so is $c(A \cap C)$. If $\Omega \subset \Omega_{\pm}$ is a shift space and $\omega^{\text{alt}} \notin \Omega$, then $c(\Omega \cap C)$ is a shift space.*

Proof. To prove the first statement we will show that if $\eta = c(\omega)$ with $\omega \in A$ then $\sigma^{\pm 1}(\eta) \in c(A \cap C)$. Consider the elements $k_{\pm 1} \in K(\omega) \subset \mathbb{Z}$, as defined in the definition of the collapsing map. We have $\sigma^{\pm 1}(\eta) = c \circ \sigma^{k_{\pm 1}}(\omega)$. Since $\omega^{\text{alt}} \notin \Omega$, all elements in $\Omega \setminus C$ are not zero-collapsible. So, $\Omega \cap C$ is the intersection of Ω with two cylinder sets. So, $\Omega \cap C$ is closed. Therefore $c(\Omega \cap C)$ is closed by the continuity of c and compactness of $\Omega \cap C$. \square

Proposition 18. *Let μ be a shift invariant measure on a shift space $\Omega \subset \Omega_{\pm}$. Then, $\mu \circ c^{-1}$ is a shift invariant measure on $c(\Omega)$.*

Proof. The content of this proposition is that $\mu \circ c^{-1}$ is shift invariant. Let $B \subset c(\Omega)$ be a Borel set and $A = c^{-1}(B)$. Recall the definition of $K(\omega) \subset \mathbb{Z}$ used in the collapsing map. Let $k_1(\omega)$ denote the smallest positive entry of $K(\omega)$. For $j \geq 1$ let $A_j = \{\omega \in A : k_1(\omega) = j\}$. Then we have $\mu \circ c^{-1}(B) = \sum_{j=1}^{\infty} \mu(A_j)$. For $\omega \in A_j$ we have $c \circ \sigma^j(\omega) = \sigma \circ c(\omega)$. Observe that $c^{-1} \circ \sigma(B) = \bigsqcup_{j=1}^{\infty} \sigma^j(A_j)$. Therefore by shift invariance of μ ,

$$\mu \circ c^{-1} \circ \sigma(B) = \sum_{j=1}^{\infty} \mu \circ \sigma^j(A_j) = \sum_{j=1}^{\infty} \mu(A_j) = \mu(B).$$

\square

5.3. Renormalization Theorems. In this section we state our most general renormalization results for the map $\Phi : X \rightarrow X$ where $X = \Omega_{\pm} \times \Omega_{\pm} \times N$ as in Section 4.2. The main results are very combinatorial, so we prove them in the next subsection. However, corollaries we state are proved to follow from the main results.

Define $\mathcal{R}_1 \subset X$ to be the set of “once renormalizable” elements of X :

$$(8) \quad \mathcal{R}_1 = \{(\omega, \omega', \mathbf{v}) : \text{both } \omega \text{ and } \omega' \text{ are collapsible}\} = C \times C \times N.$$

The renormalization mentioned is the map

$$(9) \quad \rho : \mathcal{R}_1 \rightarrow X \quad \text{given by } \rho(\omega, \omega', \mathbf{v}) = (c(\omega), c(\omega'), \mathbf{v}).$$

The manner in which ρ renormalizes the map Φ is described by the theorem below.

Before stating the theorem, we define some important subsets of X :

$$P_4 = \{(\omega, \omega', \mathbf{v}) \in X \text{ which have a stable periodic orbit of period 4}\}.$$

$$NUC = \{(\omega, \omega', \mathbf{v}) \in X : \text{either } \omega \text{ or } \omega' \text{ is not unbounded-collapsible}\}.$$

$$NS = \{(\omega, \omega', \mathbf{v}) \in X \text{ without a stable periodic orbit}\}.$$

The points in P_4 correspond to loops in a tiling of smallest possible size. See Proposition 5. The points of NUC fail to be renormalizable ($\mathcal{R}_1 \cap NUC = \emptyset$) in the most dramatic way: if $(\omega, \omega', \mathbf{v}) \in NUC$, then $(\sigma^m(\omega), \sigma^n(\omega'), \mathbf{v}) \in NUC$ for all $m, n \in \mathbb{Z}$. But, we think of NUC as a very small set. See Propositions 15 and 16.

Theorem 19 (Renormalization). *Let $\omega, \omega' \in \Omega_{\pm}$ and $\mathbf{v} \in N$. Then the following statements hold.*

- (1) $P_4 \cap \mathcal{R}_1 = \emptyset$ (stable periodic orbits of period 4 are not renormalizable.)
- (2) If $(\omega, \omega', \mathbf{v}) \in X \setminus (P_4 \cup NUC)$, then there are integers $m < 0$ and $n > 0$ for which $\Phi^m(\omega, \omega', \mathbf{v}), \Phi^n(\omega, \omega', \mathbf{v}) \in \mathcal{R}_1$. In particular, the first return map $\Phi_R : \mathcal{R}_1 \rightarrow \mathcal{R}_1$ of Φ to \mathcal{R}_1 is well defined and invertible.
- (3) If $(\omega, \omega', \mathbf{v}) \in \mathcal{R}_1$, we have $\rho \circ \Phi_R(\omega, \omega', \mathbf{v}) = \Phi \circ \rho(\omega, \omega', \mathbf{v})$.
- (4) If $(\omega, \omega', \mathbf{v}) \in \mathcal{R}_1$ has a stable periodic orbit of period larger than four, then $\rho(\omega, \omega', \mathbf{v})$ has a stable periodic orbit of strictly smaller period.

Statement (3) has the following consequence for invariant measures.

Corollary 20 (Renormalization acts on measures). *Let ν be a Φ -invariant Borel measure on X . Then $\nu \circ \rho^{-1}$ is also a Φ -invariant Borel measure.*

Proof. Let $A \subset X$ be Borel. Then statement (3) implies that $\nu \circ \rho^{-1} \circ \Phi^{-1}(A) = \nu \circ \Phi_R^{-1} \circ \rho^{-1}(A)$. Since ν is Φ invariant, its restriction to $\mathcal{R}_1 = \rho^{-1}(X)$ is also Φ_R invariant. So, $\nu \circ \rho^{-1} \circ \Phi^{-1}(A) = \nu \circ \rho^{-1}(A)$ as desired. \square

Statements (2) and (4) of the Renormalization Theorem are useful for detecting stable periodic orbits. We will say that $x \in X$ is *n times renormalizable* if $\rho^k(x)$ is well defined for all $k = 1, \dots, n$. We use $\mathcal{R}_n \subset X$ to denote the set of $(\omega, \omega', \mathbf{v})$ which are n times renormalizable. So, $\mathcal{R}_n = \rho^{-n}(X)$ for $n \geq 0$. Similarly, we say *the orbit of x is n times renormalizable* if there is an $m \in \mathbb{Z}$ such that $\Phi^m(x)$ is n times renormalizable. We use \mathcal{O}_n to denote the set of all $x \in X$ whose orbit is n times renormalizable. Note that \mathcal{O}_n is the smallest Φ -invariant set containing \mathcal{R}_n .

Suppose that $x \in \mathcal{O}_n \setminus \mathcal{O}_{n+1}$. By (2), the only explanation is that each possible $y = \rho^n \circ \Phi^m(x)$ lies in NUC or P_4 . In the latter case, we conclude by (4) that x has a stable periodic orbit. We would like to make this conclusion hold almost always, so we make the following definition.

Definition 21. Let ν be a Borel measure on X . We say ν is *robustly renormalizable* if for all integers $n \geq 0$ we have $\nu \circ \rho^{-n}(NUC) = 0$.

Assuming $\nu = \mu \times \mu' \times \mu_N$ as in Proposition 4, this is equivalent to the measures of the form $\mu \circ c^{-n}$ and $\mu' \circ c^{-n}$ never having an atom at ω^{alt} . See Proposition 16.

Corollary 22. *Suppose ν is robustly renormalizable. Then, $\nu(NS) = \lim_{n \rightarrow \infty} \nu(\mathcal{O}_n)$.*

Proof. Since ν is robustly renormalizable, by statement (4) of the Renormalization Theorem, we know that for ν -almost every $x \in X \setminus NS$ there are $m, n \in \mathbb{Z}$ with $n \geq 0$ so that $\rho^n \circ \Phi^m(x) \in P_4$. And conversely, as stated above if $\rho^n \circ \Phi^m(x) \in P_4$ we know that $x \in X \setminus NS$. Therefore $X \setminus NS$ is the smallest Φ -invariant set containing $\bigcup_{n=0}^{\infty} \rho^{-n}(P_4)$. Observe that $\rho^{-n}(P_4) = \mathcal{R}_n \setminus \mathcal{R}_{n+1}$ up to a set of ν -measure zero so that

$$X \setminus NS = \bigcup_{n=0}^{\infty} (\mathcal{O}_n \setminus \mathcal{O}_{n+1}) \quad \text{and} \quad NS = \bigcap_{n=0}^{\infty} \mathcal{O}_n.$$

This is a nested intersection, so the conclusion follows. \square

Because of this Corollary, we wish to iteratively compute the measures of the sets \mathcal{O}_n . For this, we need some understanding of the return times to \mathcal{R}_n . For non-negative $n \in \mathbb{Z}$, the *return time* of an element $x \in \mathcal{R}_n$ to \mathcal{R}_n is the smallest integer $m > 0$ for which $\Phi^m(x) \in \mathcal{R}_n$. We write $m = R_n(x)$. The existence of this number is provided by statement (2) of the Renormalization Theorem. Observe that if ν is Φ -invariant then we have

$$\nu(\mathcal{O}_n) = \int_{\mathcal{R}_n} R_n(x) d\nu(x).$$

This demonstrates the importance of knowing the return times.

The following lemma explains how return time is related to the insertion operation. Let $(\eta, \eta', \mathbf{v}) = \rho(\omega, \omega', \mathbf{v})$ so that $\eta = c(\omega)$ and $\eta' = c(\omega')$. Recall from Proposition 12 that ω can be recovered from η by an insertion operation. That is, $\omega = \mathcal{I}_f(\eta)$ for some $f : \mathbb{Z} \rightarrow \mathcal{W}$ with $f(i) = (-+)^{n_i}$ for all i . Similarly, $\omega' = \mathcal{I}_{f'}(\eta')$ for some $f' : \mathbb{Z} \rightarrow \mathcal{W}$ with $f'(i) = (-+)^{n'_i}$ for all i .

Lemma 23 (Return times). *With $(\omega, \omega', \mathbf{v}) \in \mathcal{R}_1$ as above, let $\mathbf{v} = (a, b)$ and let $\mathbf{v}' = (sb, sa)$, which is the directional component of $\Phi(\omega, \omega', \mathbf{v})$ as in equation 5. Assume $\omega = \mathcal{I}_f \circ c(\omega)$ and $\omega' = \mathcal{I}_{f'} \circ c(\omega')$ as above. The following statements give the return time of $(\omega, \omega', \mathbf{v})$ to \mathcal{R}_1 .*

- If $\mathbf{v}' = (1, 0)$ then $R_1(x) = 2\ell(f(0)) + 1$.
- If $\mathbf{v}' = (-1, 0)$ then $R_1(x) = 2\ell(f(-1)) + 1$.
- If $\mathbf{v}' = (0, 1)$ then $R_1(x) = 2\ell(f'(0)) + 1$.
- If $\mathbf{v}' = (0, -1)$ then $R_1(x) = 2\ell(f'(-1)) + 1$.

Observe that since each $f(i) = (-+)^{n_i}$, these word lengths are all multiples of 2 and the return times are all equivalent to one modulo four.

We now generalize the return time definition to a linear operator on the space \mathcal{M} of all Borel measurable functions on X . Suppose $f \in \mathcal{M}$. We define the *retraction of f to \mathcal{R}_n* to be the function $r_n(f) : \mathcal{R}_n \rightarrow \mathbb{R}$ given by

$$r_n(f; x) = \sum_{i=0}^{R_n(x)-1} f \circ \Phi^i(x).$$

We think of this as a generalization of the return time, since for the constant function $\mathbb{1}$ we have $R_n(x) = r_n(\mathbb{1}; x)$. Observe that by Φ -invariance of ν we have

$$(10) \quad \int_{\mathcal{O}_n} f d\nu = \int_{\mathcal{R}_n} r_n(f; x) d\nu.$$

The theory of conditional expectations demonstrates that for any positive ν -integrable $f : \mathcal{R}_n \rightarrow \mathbb{R}$, there is a Borel measurable function $g : X \rightarrow \mathbb{R}$ so that

$$\int_{\mathcal{R}_n} f(y) d\nu(y) = \int_X g(x) d\nu \circ \rho^{-n}(x).$$

This function g is the *conditional expectation* of $f(x)$ given $\rho^n(x)$, and it is uniquely defined $\nu \circ \rho^{-n}$ -a.e.. See Chapter 27 of [Loè78], for example.

We now combine the theory of conditional expectations with our retraction operator. For $f : X \rightarrow \mathbb{R}$ Borel measurable and ν a Φ -invariant, define $C(\nu, n)(f) : X \rightarrow \mathbb{R}$ to be the *conditional expectation of the retraction of f to \mathcal{R}_n* . That is, $C(\nu, n)(f)$ is the $\nu \circ \rho^{-n}$ -a.e. unique Borel measurable function such that for all Borel $B \subset X$ we have

$$(11) \quad \int_{\rho^{-n}(B)} r_n(f; x) d\nu(x) = \int_B C(\nu, n)(f)(x) d\nu \circ \rho^{-n}(x).$$

In particular, taking $B = X$ we see $C(\nu, n) : L^1(\nu) \rightarrow L^1(\nu \circ \rho^{-n})$. Observe that $C(\nu, 0)$ may be interpreted as the identity operator ν -a.e., and $C(\nu, n)$ satisfies the following cocycle equation for integers $m, n \geq 0$.

$$(12) \quad C(\nu, m+n)(f) = C(\nu \circ \rho^{-n}, m) \circ C(\nu, n)(f) \quad \nu \circ \rho^{-m-n}\text{-a.e.}$$

In particular, we may write

$$(13) \quad C(\nu, n) = C(\nu \circ \rho^{n-1}, 1) \circ C(\nu \circ \rho^{n-2}, 1) \circ \cdots \circ C(\nu, 1).$$

So to evaluate the cocycle it is sufficient to understand the operators $C(\nu \circ \rho^n, 1)$.

We summarize our approach by restating Corollary 22 with this language, which is our approach to proving results such as Theorem 2. (This will be equally important for similar results involving polygon exchange maps in [?].) Observe that by Equations 10 and 11, for any Borel measurable f we have

$$(14) \quad \int_{\mathcal{O}_n} f d\nu = \int_{\mathcal{R}_n} r_n(f, x) d\nu(x) = \int_X C(\nu, n)(f)(x) d\nu \circ \rho^{-n}(x).$$

Specializing to the constant function, we obtain the following.

Corollary 24 (Main Approach). *Suppose ν is robustly renormalizable. Let $\mathbb{1}(x) = 1$ for all $x \in X$. Then for all n ,*

$$\nu(\mathcal{O}_n) = \int_X C(\nu, n)(\mathbb{1})(x) d\nu \circ \rho^{-n}(x).$$

and $\nu(NS) = \lim_{n \rightarrow \infty} \nu(\mathcal{O}_n)$.

For general ν , this limit is probably impossible to evaluate. But, for the measures associated to Theorem 2, the situation is very nice. In particular, we will be studying robustly renormalizable measures ν with the property that there is a finite dimensional subspace $L \subset \mathcal{M}$ such that $\mathbb{1} \in L$ and $C(\nu, n)(f) \in L$ for all $f \in L$. Such a reduction reduces the problem to studying a cocycle over a finite dimensional vector space.

In the cases of interest, we partition the space X into six non-empty pieces $\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_6$ and define the linear embedding $\epsilon : \mathbb{R}^6 \rightarrow \mathcal{M}$ by $\epsilon(\mathbf{p})(x) = \mathbf{p}_i$ if $x \in \mathcal{S}_i$, and

$$(15) \quad L = \{\epsilon(\mathbf{p}) : \mathbf{p} \in \mathbb{R}^6\}.$$

We say $x \in \mathcal{S}_i$ has *step class i* . This term is defined in the three paragraphs below.

Let $x = (\omega, \omega', \mathbf{v}) \in X$ be arbitrary. A *step* will indicate information which depends only on information at the origin, and the next square visited by the curve through the normal \mathbf{v} leaving the square centered at the origin. Define $(\eta, \eta', \mathbf{v}') = \Phi(\omega, \omega', \mathbf{v})$. If $\mathbf{v}' = (1, 0)$ or $\mathbf{v}' = (-1, 0)$, we call x a *horizontal step*, otherwise we call x a *vertical step*. Note that if x is part of a horizontal step, then $\omega' = \eta'$, but $\eta = \sigma^{sb}(\omega)$ with $s = \omega_0\omega'_0$ so that $sb \in \{\pm 1\}$. See equation 5.

We divide the classes of horizontal and vertical steps into smaller classes. We call $x = (\omega, \omega', \mathbf{v})$ a $\omega_0\omega_1$ -*horizontal step* if $sb = 1$ and a $\omega_{-1}\omega_0$ -*horizontal step* if $sb = -1$. So, we have defined the term w -*horizontal step* for each word w of length 2, i.e. $w \in \{--, -+, +-, ++\}$. If x is either a $++$ -horizontal steps or a $--$ -horizontal steps, then we call x a *matching horizontal step*. Similarly, if x is a vertical step, then $\eta' = \sigma^{sa}(\omega')$. If $sa = 1$ we define x to be a $\omega'_0\omega'_1$ -*vertical step*, and if $sa = -1$ we define x to be a $\omega'_{-1}\omega'_0$ -*vertical step*. If x is either a $++$ -vertical step or a $--$ -vertical step, we call x a *matching vertical step*.

We say x has *step class 1* if x is a $-+$ -horizontal step, has *step class 2* if x is a $+-$ -horizontal step, has *step class 3* if x is a matching horizontal step, has *step class 4* if x is a $-+$ -vertical step, has *step class 5* if x is a $+-$ -vertical step, and has *step class 6* if x is a matching vertical step. This defines the six sets $\mathcal{S}_1, \dots, \mathcal{S}_6 \subset X$, and the subspace $L \subset \mathcal{M}$ as in equation 15.

For the following lemma define χ_i to be the characteristic function of \mathcal{S}_i , and define $\mathbf{e}_i \in \mathbb{R}^6$ to be the standard basis vector with 1 in position i .

Lemma 25 (Collapsed Steps). *Suppose $x \in \mathcal{R}_1$ has return time $R_1(x) = 4m + 1$ and $\rho(x) \in \mathcal{S}_j$. Then, for all $i \in \{1, \dots, 6\}$ we have $r_1(\chi_i; x) = \mathbf{e}_j^T M \mathbf{e}_i$ with*

$$M = \begin{bmatrix} m & m-1 & 2 & 0 & 0 & 2m \\ m & m+1 & 0 & 0 & 0 & 2m \\ m & m & 1 & 0 & 0 & 2m \\ 0 & 0 & 2m & m & m-1 & 2 \\ 0 & 0 & 2m & m & m+1 & 0 \\ 0 & 0 & 2m & m & m & 1 \end{bmatrix}.$$

Observe that the j -th row of M give the number of each step type which appears in the set $\{x, \Phi(x), \dots, \Phi^{4m+1}(x)\}$ provided $\rho(x) \in \mathcal{S}_j$ and $R_1(x) = 4m + 1$. This lemma is restated and proved as Lemma 35.

The following Corollary is a main tool in the proofs of Theorem 2 and for subsequent work on polygon exchange maps [?].

Corollary 26. *Suppose ν is a measure on X such that for all $j \in \{1, \dots, 6\}$ the conditional expectation of $R_1(x)$ given that $\rho(x) \in \mathcal{S}_j$ is a constant $4m_j + 1$ at ν -a.e. point of $\rho^{-1}(\mathcal{S}_j)$. Then $C(\nu, 1) \circ \epsilon(\mathbf{p}) \in L$ for all $\mathbf{p} \in L$, and $\nu \circ \rho^{-1}$ -a.e. we have $C(\nu, 1) \circ \epsilon(\mathbf{p}) = \epsilon(M' \mathbf{p})$ where*

$$M' = \begin{bmatrix} m_1 & m_1-1 & 2 & 0 & 0 & 2m_1 \\ m_2 & m_2+1 & 0 & 0 & 0 & 2m_2 \\ m_3 & m_3 & 1 & 0 & 0 & 2m_3 \\ 0 & 0 & 2m_4 & m_4 & m_4-1 & 2 \\ 0 & 0 & 2m_5 & m_5 & m_5+1 & 0 \\ 0 & 0 & 2m_6 & m_6 & m_6 & 1 \end{bmatrix}.$$

Proof. Since $r_1(\chi_i; x) = \mathbf{e}_j \cdot M \mathbf{e}_i$ for $x \in \mathcal{S}_j$ with M as in the above lemma and $m = m(x)$ defined so that $R_1(x) = 4m+1$. Note then that $r_1(\chi_i; x) = a_{i,j}m(x) + b_{i,j}$ for some $a_{i,j}, b_{i,j} \in \mathbb{Z}$

coming from the entries of M . Then, by definition of $C(\nu, 1)$, for all $i, j \in \{1, \dots, 6\}$ and all $B \subset \mathcal{S}_j$ we have

$$(16) \quad \int_{\rho^{-1}(B)} a_{i,j}m(x) + b_{i,j} d\nu(x) = \int_B C(\nu, 1)(\chi_i)(x) d\nu \circ \rho^{-n}(x).$$

By definition of m_j and because we defined $m(x)$ so that $R_1(x) = 4m(x) + 1$,

$$(17) \quad \int_{\rho^{-1}(B)} 4m(x) + 1 d\nu(x) = \int_B 4m_j + 1 d\nu \circ \rho^{-n}(x) \quad \text{for all Borel } B \subset \mathcal{S}_j.$$

Therefore, we see that $C(\nu, 1)(\chi_i)(x) = a_{i,j}m_j + b_{i,j}$ satisfies the equation 16. This determines $C(\nu, 1)(\chi_i)(x)$ by a.e.-uniqueness of conditional expectations. Finally, we can extend to all of the subspace $L \subset \mathcal{M}$ by linearity of the operator $C(\nu, 1)$. \square

Observe that to evaluate the integral of a function of the form $\epsilon(\mathbf{p})$ with respect to some measure ν , it suffices to know the measures of the step classes. That is,

$$(18) \quad \int_X \epsilon(\mathbf{p})(x) d\nu = \sum_{i=1}^6 \nu(\mathcal{S}_i) \mathbf{p}_i.$$

We give formulas for these measures in two cases below.

Proposition 27. *Let $\nu = \mu \times \mu' \times \mu_N$ where μ and μ' are shift invariant measure on Ω_{\pm} . Then,*

$$\nu(\mathcal{S}_1) = \frac{1}{2}\mu(\mathcal{C}(-+)), \quad \nu(\mathcal{S}_2) = \frac{1}{2}\mu(\mathcal{C}(+-)), \quad \text{and} \quad \nu(\mathcal{S}_3) = \frac{1}{2}\mu(\mathcal{C}(--) \cup \mathcal{C}(++)).$$

$$\nu(\mathcal{S}_4) = \frac{1}{2}\mu'(\mathcal{C}(-+)), \quad \nu(\mathcal{S}_5) = \frac{1}{2}\mu'(\mathcal{C}(+-)), \quad \text{and} \quad \nu(\mathcal{S}_6) = \frac{1}{2}\mu'(\mathcal{C}(--) \cup \mathcal{C}(++)).$$

In addition, for the restriction of ν to P_4 we have

$$\nu(\mathcal{S}_1 \cap P_4) = \nu(\mathcal{S}_5 \cap P_4) = \mu(\mathcal{C}(-+))\mu'(\mathcal{C}(+-)), \quad \text{and}$$

$$\nu(\mathcal{S}_2 \cap P_4) = \nu(\mathcal{S}_4 \cap P_4) = \mu(\mathcal{C}(+-))\mu'(\mathcal{C}(-+)).$$

Also $\nu(\mathcal{S}_3 \cap P_4) = \nu(\mathcal{S}_6 \cap P_4) = 0$.

5.4. Proofs of the Renormalization Theorems. In this section we prove the renormalization theorems of the previous section. Since this section contains no substantially new results, it may be skipped by a reader disinterested in these proofs. If the reader just wishes to understand why the system is renormalizable, he/she may read the first few paragraphs of the section and attempt to understand Figures 1 and 2.

Our proofs are primarily based on analysis of tilings rather than the map $\Phi : X \rightarrow X$. This is motivated by the natural point of view that the dynamics of Φ correspond to following curves in the associated tiling. All proofs in this section utilize this philosophy. Therefore, we fix a tiling $[\tau_{\omega, \omega'}]$ once and for all.

In the definition of the collapsing map, we utilized a subset $K(\omega) \subset \mathbb{Z}$ which indicated the places to remove symbols under the collapsing map. See equation 7, and observe that $K(\omega)$ is well defined for all $\omega \in \Omega_{\pm}$. We define $\bar{K} = K(\omega) \times K(\omega')$ and call this set the (*centers of the*) *kept squares*.

The squares with centers in $\mathbb{Z}^2 \setminus \bar{K}$ form a family of rows and columns. These are the gray squares in Figures 1 and 2. On the level of tilings, the tiling associated to the image $\rho(\omega, \omega', \mathbf{v})$ is $[\tau_{c(\omega), c(\omega')}]$. This tiling can be obtained from $[\tau_{\omega, \omega'}]$ by removing all columns

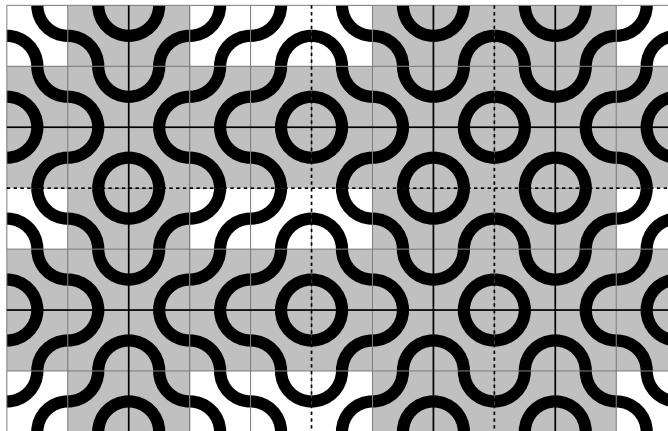


FIGURE 2. The set \overline{K} consists of the indices of white squares.

consisting of squares whose centers lie in $\mathbb{Z}^2 \setminus \overline{K}$. Then slide the remaining columns together to reconstruct a Truchet tiling. The remaining squares whose centers were in $\mathbb{Z}^2 \setminus \overline{K}$ consist of a family of rows of squares. Again, remove these and slide the rows together.

Remark 28. *Observe that the renormalized tiling is defined modulo translation if ω and ω' are unbounded-collapsible. To define the new tiling precisely, we need ω and ω' to also be zero-collapsible. In this section we will only need ω and ω' to be unbounded-collapsible.*

To analyze this process, we introduce the following definition.

Definition 29. Let m be an integer. The line $x = m + \frac{1}{2}$ is a *vertical $-+$ -dividing line* if $\omega_m = -1$ and $\omega_{m+1} = 1$. Similarly, $x = m + \frac{1}{2}$ is a *vertical $+-$ -dividing line* if $\omega_m = 1$ and $\omega_{m+1} = -1$. The line $y = m + \frac{1}{2}$ is a *horizontal $-+-$ or $+-$ -dividing line* if $\omega'_m = -1$ and $\omega'_{m+1} = 1$ or $\omega'_m = 1$ and $\omega'_{m+1} = -1$, respectively.

The $-+$ -dividing line for the tiling shown in figure 2 are drawn as darkened solid lines. The $+-$ -dividing lines are shown as dashed lines. The following can be observed by the reader.

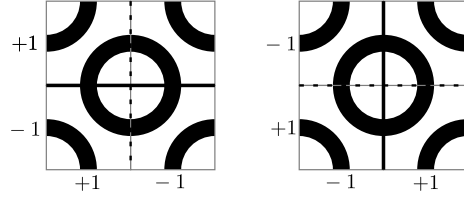
Proposition 30. *The squares indexed by elements of $\mathbb{Z}^2 \setminus \overline{K}$ are those squares in the 1-neighborhood of a $-+$ -dividing line.*

We can also connect these dividing lines to the paths which close up after visiting exactly four squares.

Proposition 31. *An arc of a tile in the tiling $[\tau_{\omega, \omega'}]$ is part of a closed path which visits only four squares if and only if the arc joins two dividing lines with differing signs (e.g. the arc starts on a $-+$ -horizontal dividing line and ends on $+-$ -vertical dividing line.)*

This statement also implies statement (1) of the Renormalization Theorem.

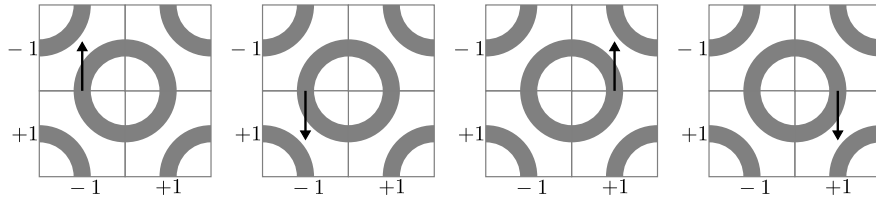
Proof. Consider such a path in $[\tau_{\omega, \omega'}]$. Observe that such a path corresponds to a choice of $m, n \in \mathbb{Z}$ for which $\omega_m \omega'_n = -1 = \omega_{m+1} \omega'_{n+1}$ and $\omega_{m+1} \omega'_n = 1 = \omega_m \omega'_{n+1}$. Therefore either $\omega_m = 1 = \omega'_{n+1}$ and $\omega_{m+1} = -1 = \omega'_n$, or $\omega_{m+1} = 1 = \omega'_n$ and $\omega_m = -1 = \omega'_{n+1}$. See the figure below, where values of ω are written below the tiles, and values of ω' are written to the left.



In both cases, two dividing lines of opposite sign description pass through the center of the circular path. \square

We can also use this observation to prove Proposition 27.

Proof of Proposition 27. The values of $\nu(\mathcal{S}_i)$ follow trivially from the definitions of the step classes. We concentrate on the intersections of the step classes with P_4 . Suppose $x \in \mathcal{S}_1 \cap P_4$, i.e. x is a $-+$ -horizontal step. Then, there are four possible local pictures for the loop associated to x . These possibilities are shown below.

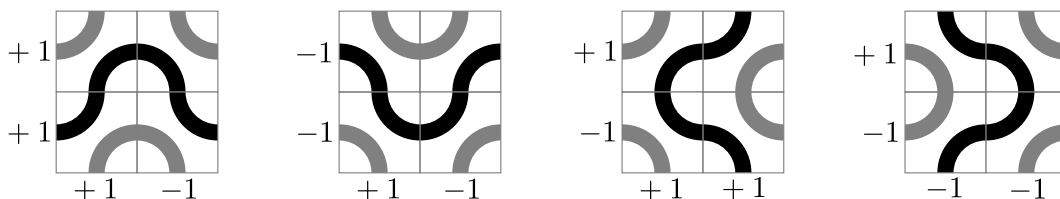


Above, the arrow lies in the square which should be centered at the origin and represents the choice of the normal vector. Observe that the probability of any of these local pictures occurring is given by $\frac{1}{4}\mu(\mathcal{C}(-+))\mu'(\mathcal{C}(+-))$, with the factor of $\frac{1}{4}$ coming from μ_N . The other cases are similar. \square

The following lemma is the main observation in the proofs of the remaining Renormalization results.

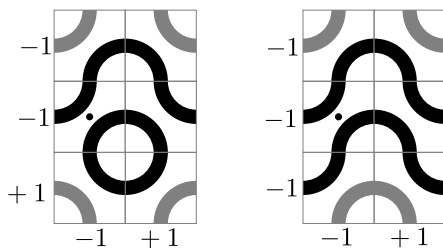
Lemma 32 (Crossing dividing lines). *Let α be an arc of a square whose center lies in $\mathbb{Z}^2 \setminus \overline{K}$. If α is not part of a loop which visits only four squares, then α is part of a path γ contained in a 2×2 square which visits four squares and joins the two boundaries components of either the 1-neighborhood of a $-+$ -horizontal or the 1-neighborhood of a $-+$ -vertical dividing line. In the first case, the endpoints of γ differ by a vertical translation by 2, the two endpoints do not lie in the 1-neighborhood of a $-+$ -vertical dividing line, and the values of ω taken on the x -coordinates of centers of the four squares visited by γ agree. In the second case, the endpoints of γ differ by a horizontal translation by 2, the two endpoints do not lie in the 1-neighborhood of a $-+$ -horizontal dividing line, and the values of ω' taken on the y -coordinates of centers of the four squares visited by γ agree.*

The lemma was crafted to indicate that the local picture of the tiling at the squares visited by γ is determined by one of the four pictures below. The possible curves γ are drawn in black below. The left two cases cross $-+$ -vertical dividing lines.



Proof. Since α lies a square whose center lies in $\mathbb{Z}^2 \setminus \overline{K}$, it lies in the 1-neighborhood of either a $-+-$ -horizontal dividing line or a $-+-$ -vertical dividing line. See Proposition 30. We break into cases based on this.

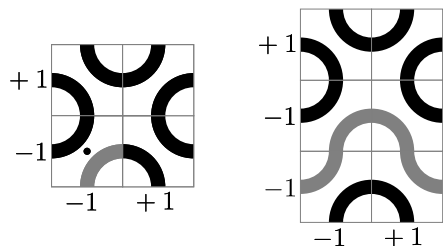
First suppose that α belongs to a 1-neighborhood of a $-+-$ -vertical dividing line but not to a 1-neighborhood of a $-+-$ -horizontal dividing line. Assume the center of the square containing α is (m, n) , and that this square lies to the left of this vertical line. Then, $\omega_m = -1$ and $\omega_{m+1} = 1$. Consider the case when $\omega'_n = -1$. Since the square centered at (m, n) is not in the 1-neighborhood of a $-+-$ -horizontal dividing line, we have $\omega'_{n+1} = -1$. We draw two local pictures, with the left case $\omega'_{n-1} = 1$ and the right case $\omega'_{n-1} = -1$. These cases are drawn on the left and right below, respectively, with a dot placed at (m, n) .



The arcs α under consideration are the ones that start in the squares with a dot. Observe that unless the arc is part of a loop of length four, the four black arcs connected to α join opposite sides of the 1-neighborhood of the $-+-$ -vertical dividing line (the central vertical line). The case of $\omega'_n = 1$ is similar, and produces the same pictures but reflected with respect to the x -axis. The case where (m, n) is to the right of the dividing line is also similar: just move the dot one square to the right.

The case where α belongs to the neighborhood of a $-+-$ -horizontal dividing line and not to the neighborhood of a $-+-$ -vertical dividing line differs by a reflection in the line $y = x$.

Finally, we suppose that the square with center (m, n) containing α lies in both the 1-neighborhood of a $-+-$ -horizontal dividing line and the 1-neighborhood of a $-+-$ -vertical dividing line. The intersections of the 1-neighborhoods form a 2×2 square as depicted on the left below.



We will assume that α is the gray arc in the above left picture, and (m, n) is the coordinates of the dot. The other cases will be similar. In this case, $\omega_m = -1$, $\omega_{m+1} = 1$ and $\omega'_n = -1$. If $\omega'_{n-1} = 1$, then $y = m - \frac{1}{2}$ is a $+--$ -horizontal dividing line, and by Proposition 31 we know α is part of loop visiting four squares. Therefore, we may assume $\omega'_{n-1} = -1$. In this case, the gray arc extends to a curve of length four crossing the neighborhood of the vertical dividing line as on the right side. \square

The following is equivalent to the remaining three statements of the Renormalization Theorem.

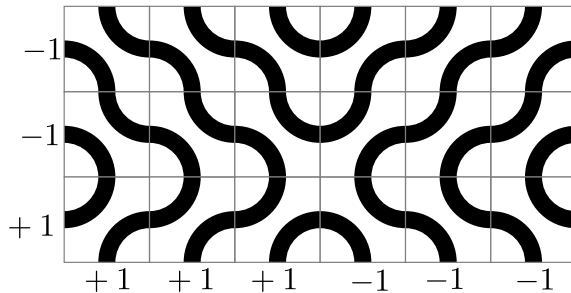
Theorem 33. *Assume ω and ω' are unbounded-collapsible.*

- (2) *There is no infinite connected union of arcs of tiles contained entirely in squares with centers in $\mathbb{Z}^2 \setminus \overline{K}$.*
- (3) *If γ is a curve of the associated tiling, then collapsing the 1-neighborhoods of the $-+$ -dividing lines slides the arcs of tiles with centers in \overline{K} together so that the images of the arcs of γ form a curve in $[\tau_{c(\omega), c(\omega')}]$, with the natural cyclic or linear ordering of these arcs respected. (The type of ordering depends if γ is closed or bi-infinite.)*
- (4) *No closed curve of the tiling consists entirely of arcs of tiles with centers in \overline{K} .*

Proof. Consider statement (2). Suppose we had such a union of arcs. Choose one of the arcs, α . By the Lemma, it is part of a union of four arcs γ which crosses a $-+$ -dividing line. Without loss of generality, assume that this dividing line is vertical. The endpoints of γ differ by a horizontal translation by 2 and lie outside of any 1--neighborhood of a $-+$ -horizontal dividing lines. Without loss of generality, assume that the infinite union of arcs continues to the right. We observe that because the endpoints were not in a 1--neighborhood of a $-+$ -horizontal dividing lines, the next square to the right of the right endpoint of γ cannot lie within the 1--neighborhood. By assumption, this square must lie in the 1--neighborhood of a $-+$ -vertical dividing line. The curve traverses this neighborhood after visiting another four squares. We see by induction that the infinite union of arcs crosses an contiguous infinite sequence of 1--neighborhoods of $-+$ -vertical dividing lines. Therefore ω terminates in the infinite word $(-+)^{\infty}$, which shows that ω is not unbounded-collapsible.

Statement (3) also follows from the lemma. The collections of four arcs crossing 1-neighborhoods of $-+$ -dividing lines are collapsed.

Statement (4) follows from understanding the maximal contiguous collections of tiles with centers in \overline{K} . Such a collection arises from choosing integers $a \leq b$ and $c \leq d$ such that $\omega_a \dots \omega_b$ and $\omega'_c \dots \omega'_d$ consist of words in the set $\{(+)^i(-)^j : i \geq 0 \text{ and } j \geq 0\}$. We leave it to the reader to check no such region contains closed loops. See the example below.



□

The following implies the Return times lemma.

Lemma 34 (Restated Return times Lemma). *Suppose that ω and ω' are unbounded-collapsible. Suppose $(m, n) \in \overline{K}$ and $\mathbf{v}' \in N = \{(1, 0), (-1, 0), (0, 1), (0, -1)\}$ is a vector. By the unbounded-collapsible property, we can define $k \in \mathbb{Z}$ as follows:*

- (1) *If $\mathbf{v}' = (1, 0)$, k is the smallest non-negative integer for which $\omega_{n+1} \dots \omega_{n+2k} = (-+)^k$.*
- (2) *If $\mathbf{v}' = (-1, 0)$, k is the smallest non-negative integer for which $\omega_{n-2k} \dots \omega_{n-1} = (-+)^k$.*
- (3) *If $\mathbf{v}' = (0, 1)$, k is the smallest non-negative integer for which $\omega'_{n+1} \dots \omega'_{n+2k} = (-+)^k$.*

- (4) If $\mathbf{v}' = (-1, 0)$, k is the smallest non-negative integer for which $\omega'_{n-2k} \dots \omega'_{n-1} = (-+)^k$.

Then, the curve of the tiling leaving the tile centered at (m, n) and entering the tile centered at $(m, n) + \mathbf{v}'$ visits $4k$ tiles in $\mathbb{Z}^2 \setminus \overline{K}$ (starting at $(m, n) + \mathbf{v}'$) before returning to \overline{K} .

Proof. Assume we are in case (1), $\mathbf{v}' = (1, 0)$. If $(m+1, n) \in \overline{K}$, then by definition of \overline{K} we have $\omega_{m+1}\omega_{m+2} \neq -+$. So, $k = 0$, and this agrees to the number of squares encountered before returning to \overline{K} : zero. Now suppose $(m+1, n) \notin \overline{K}$. Since $(m, n) \in \overline{K}$, it must be that $\omega_{m+1}\omega_{m+2} = -+$, so k is at least one. We apply the Crossing Dividing Lines Lemma to see that after visiting four squares in $\mathbb{Z}^2 \setminus \overline{K}$, the curve enters the tile centered at $(m+3, n)$. If this square is in \overline{K} we must have $\omega_{m+1} \dots \omega_{m+4} \neq (-+)^2$, and we have proved the Lemma with $k = 1$. Otherwise, if $(m+3, n) \notin \overline{K}$ we have $\omega_{m+1} \dots \omega_{m+4} = (-+)^2$. We may repeat this argument inductively. Since ω is unbounded-collapsible, eventually $\omega_{n+1} \dots \omega_{n+2k} \neq (-+)^k$. \square

Finally, we consider the Collapsed Steps Lemma. For this we make a definition to parallel the definitions of “steps.” Indeed the following definition seems more natural. A *domino* is an unordered pair $D = \{(m, n), (m', n')\}$ with $m, m', n, n' \in \mathbb{Z}$ and $(m, n) - (m', n') \in N$ (i.e. the squares centered at these points are adjacent). We say D is *horizontal* if $(m, n) - (m', n') \in \{(1, 0), (-1, 0)\}$ and *vertical* otherwise.

A horizontal (resp. vertical) domino $D = \{(m, n), (m', n')\}$ is *in standard position* if $m' = m + 1$ (resp. $n' = n$). For this paragraph we assume all dominoes are in standard position. Given ω and ω' as in this section, we say that a horizontal (resp. vertical) domino D is a $\omega_m\omega_{m+1}$ -horizontal domino (resp. $\omega'_n\omega'_{n+1}$ -vertical domino). As with the definition of steps, the quantities $\omega_m\omega_{m+1}$ and $\omega'_n\omega'_{n+1}$ are viewed as words of length 2. If D is a $++$ - or $--$ -horizontal domino, we call it a *matching horizontal domino*. We make the analogous definition of *matching vertical domino*.

Suppose that γ is a finite connected union of arcs of tiles. Then γ visits a sequence of tiles with centers listed $(m_1, n_1), \dots, (m_k, n_k)$, written in the order the tiles are visited. Then each pair $\{(m_i, n_i), (m_{i+1}, n_{i+1})\}$ is a domino. We write $\mathcal{D}(\gamma)$ for the collection of such dominoes. (There are $k - 1$ such dominoes.) The *domino vector of the path* γ is the element $\mathbf{d} = (\mathbf{d}_1, \dots, \mathbf{d}_6) \in \mathbb{Z}^6$, where \mathbf{d}_1 is the number of $-+$ -horizontal dominoes, \mathbf{d}_2 is the number of $+-$ -horizontal dominoes, \mathbf{d}_3 is the number of matching horizontal dominoes, \mathbf{d}_4 is the number of $-+$ -vertical dominoes, \mathbf{d}_5 is the number of $+-$ -vertical dominoes, and \mathbf{d}_6 is the number of matching vertical dominoes.

We will now state a lemma equivalent to the Collapsed Steps Lemma. Suppose γ is a finite connected union of at least two arcs of tiles which begins and ends at a tile whose center lies in \overline{K} , but for which no other visited tile has a center lying in \overline{K} . By Lemma 34, γ visits a total of $4k + 2$ squares for some integer $k \geq 0$. The renormalization removes all the squares of γ except for the first and the last tile, and slides these tiles together forming a domino. We call this the *domino of* γ and denote it D_γ . (This is well defined. See Remark 28.)

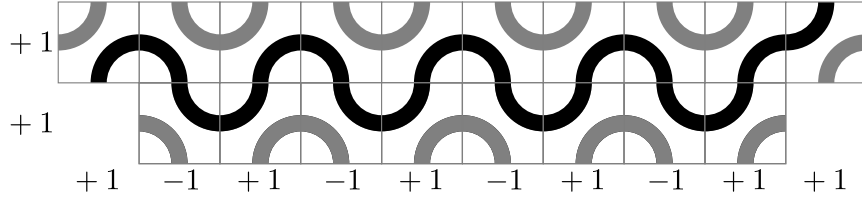
Lemma 35 (Collapsing Dominos Lemma). *Suppose that ω and ω' are unbounded-collapsible. Let γ and k be as in the previous paragraph. Then the domino vector \mathbf{d} of γ is determined by k and the domino of γ , D_γ .*

- (1) If D_γ is a $-+$ -horizontal domino then $\mathbf{d} = (k, k - 1, 2, 0, 0, 2k)$.
- (2) If D_γ is a $+-$ -horizontal domino then $\mathbf{d} = (k, k + 1, 0, 0, 0, 2k)$.

- (3) If D_γ is a matching horizontal domino then $\mathbf{d} = (k, k, 1, 0, 0, 2k)$.
- (4) If D_γ is a $-+-$ -vertical domino then $\mathbf{d} = (0, 0, 2k, k, k - 1, 2)$.
- (5) If D_γ is a $+--$ -vertical domino then $\mathbf{d} = (0, 0, 2k, k, k + 1, 2)$.
- (6) If D_γ is a matching vertical domino then $\mathbf{d} = (0, 0, 2k, k, k, 1)$.

Proof. This is again implied by Lemma 32. We consider the horizontal case. The vertical case follows by symmetry. In the case where $k = 0$, we have that the collection of dominoes along the curve is $\mathcal{D}(\gamma) = \{D_\gamma\}$. When D_γ is a $-+-$ -horizontal domino it can not satisfy the conditions of the lemma because the whole domino lies in $\mathbb{Z}^2 \setminus \overline{K}$. This proves the case $k = 0$.

Now suppose $k > 0$. Orient γ from left to right. We assume γ starts at a tile centered at (m, n) . By Lemma 32 it ends at a tile centered at $(m + 2k + 1, n)$. This makes D_γ a $\omega_m \omega_{m+2k+1}$ -horizontal domino. We observe that the first domino in $\mathcal{D}(\gamma)$ is a $\omega_m \omega_{m+1} = \omega_m -$ -horizontal domino. Similarly, the last domino is a $+\omega_{m+2k+1}$ -horizontal domino. The remaining collection of dominoes consists of k $-+-$ -horizontal dominoes, $k - 1$ $+--$ -horizontal dominoes, and $2k$ -matching vertical dominoes. See the image below for the case when ω' takes the value $+1$ on path γ . By inspection, we observe that the first three possible conclusions of the lemma hold.



□

6. RANDOM TILINGS

In this section we prove theorem 2 involving tilings generated by random elements of the shift space Ω_\pm .

For $0 \leq p \leq 1$, we will define a Borel probability measure μ_p on Ω_\pm . The measure μ_p is the shift-invariant measure such that

- (1) $\mu_p(\{\omega \in \Omega_\pm : \omega_0 = 1\}) = \frac{1}{2}$,
- (2) the conditional expectation that $\omega_0 = \omega_1$ given the values of ω_n for $n \leq 0$ is p , and
- (3) the conditional expectation that $\omega_0 = \omega_1$ given the values of ω_n for $n \geq 1$ is p .

Statement (2) is equivalent to the statement that for any Borel set $A \subset \Omega_\pm$, with the property that for any $\omega \in A$ and any function $f : \{1, 2, \dots\} \rightarrow \{\pm 1\}$ the element $\eta^f \in A$ where $\eta_n^f = \omega_n$ if $n \leq 0$ and $\eta_n^f = f(n)$ whenever $n > 0$, we have

$$(19) \quad \mu_p(\{\omega \in A : \omega_0 = \omega_1\}) = p\mu_p(A).$$

This definition indicates that a random element of Ω_\pm taken with respect to μ_p can be constructed as described above Theorem 2 in the introduction. Recall the definition of the cylinder set $\mathcal{C}(f)$ in Section 4.1. We have the following.

Proposition 36. *Given any p with $0 \leq p \leq 1$, there is a unique shift-invariant Borel probability measure μ_p satisfying statements (1)-(3) above. Let $f : \{m, \dots, n\} \rightarrow \mathbb{Z}^2 \rightarrow \{\pm 1\}$*

be arbitrary, and $\mathcal{C}(f)$ be the associated cylinder set. Then,

$$(20) \quad \mu_p(\mathcal{C}(f)) = \frac{1}{2}p^k(1-p)^{m-n-k}$$

where k is the number of integers i with $m \leq i < n$ and $f(i) = f(i+1)$.

Note that by Carathéodory's extension theorem, the measure μ_p is uniquely determined by the measures of cylinder sets. We leave it to the reader to check that $\mu_p(\mathcal{C}(f))$ must be as described, and that this function satisfies the conditions of Carathéodory's theorem.

6.1. The collapsing map. Recall the definition of the collapsing map given in Section 5.2. In particular, recall Proposition 18: $\mu \circ c^{-1}$ is a shift-invariant measure whenever μ is. In fact the collection of measures $\{\mu_p : 0 < p \leq 1\}$ is invariant under this operation up to scaling.

Theorem 37. For $0 \leq p \leq 1$, let $q = \frac{1}{2-p}$. Then, $\mu_p \circ c^{-1} = p\mu_q$.

Observe that for $p \neq 0$, the measures $\mu_p \circ c^{-n}$ converge as $n \rightarrow \infty$ after being rescaled to probability measures to the measure μ_1 . In particular, the renormalization dynamics here are not recurrent.

Proof. We ignore the cases where $p = 0$ and $p = 1$. The measure μ_0 is supported on $\{\omega^{\text{alt}}, \sigma(\omega^{\text{alt}})\}$, and the measure μ_1 is supported on the two constant sequences. These cases are trivial.

First we observe that $\mu_p \circ c^{-1}(\Omega_{\pm}) = p$. This will prove that $\mu_p \circ c^{-1}$ is p times a probability measure. Equation 20 can be used to demonstrate that the measure of the collection of those ω which are not unbounded collapsible is zero. Therefore, the measure of the collapsible elements of Ω_{\pm} equals the measure of the zero-collapsible elements. Recall that C denotes the set of all collapsible elements of Ω_{\pm} . By definition of zero-collapsible, the measure of the collection of non-zero-collapsible elements of Ω_{\pm} is the sum of the measures of two cylinder sets, so that

$$\mu_p(\Omega_{\pm} \setminus C) = \mu(\mathcal{C}(\widehat{-+})) + \mu(\mathcal{C}(-\widehat{+})) = 1 - p,$$

and $\mu_p \circ c^{-1}(\Omega_{\pm}) = \mu_p(C) = p$.

Let ν be the probability measure $\frac{1}{p}\mu_p \circ c^{-1}$. We will prove that $\nu = \mu_q$. By Proposition 36 it is sufficient to show that ν satisfies statements (1)-(3) of the definition of μ_q . Observe

$$\frac{1}{p}\mu_p \circ c^{-1}(\mathcal{C}(\widehat{+})) = \frac{1}{p}\mu_p(\mathcal{C}(+\widehat{+}))$$

by Corollary 13. Using Proposition 36, we evaluate $\mu_p(\mathcal{C}(+\widehat{+})) = \frac{p}{2}$ as desired.

We now prove that ν satisfies statement (2) in the definition of μ_q . Statement (3) has a similar proof. Define \mathcal{A} to be the σ -algebra generated by cylinder sets $\mathcal{C}(f)$ where $f : \{m, \dots, n\} \rightarrow \{\pm 1\}$ and $n \leq 0$. By equation 19, it is enough to show that for all $B \in \mathcal{A}$,

$$(21) \quad \nu(\{\omega \in B : \omega_0 = \omega_1\}) = \frac{1}{2-p}\nu(B).$$

Note that the right hand side of the equation then evaluates to $\frac{1}{p(2-p)}\mu_p \circ c^{-1}(B)$. We will show this equals the left hand side. Simplifying the left side yields

$$\nu(\{\omega \in B : \omega_0 = \omega_1\}) = \frac{1}{p}\mu_p \circ c^{-1}(\{\omega \in B : \omega_0 = \omega_1\}).$$

We will try to understand $c^{-1}(\{\omega \in B : \omega_0 = \omega_1\})$. For each $n \geq 0$ define the two cylinder sets

$$S_n^+ = \mathcal{C}(+\widehat{+}(-+)^n+) \quad \text{and} \quad S_n^- = \mathcal{C}(\widehat{-}(-+)^n-).$$

From Corollary 13, and the definition of the collapsing map, we have

$$\bigcup_{n=1}^{\infty} S_n^+ \cup S_n^- = \{\omega : \omega \text{ is collapsible and } c(\omega)_0 = c(\omega)_1\} \quad \mu_p\text{-almost everywhere.}$$

(An $\omega \in S_n^\pm$ is zero-collapsible but not necessarily unbounded-collapsible, and the non-unbounded-collapsible ω form a set of measure zero.) Since this union is disjoint, we have

$$(22) \quad \frac{1}{p} \mu_p \circ c^{-1}(\{\omega \in B : \omega_0 = \omega_1\}) = \frac{1}{p} \sum_{n=0}^{\infty} \mu_p(c^{-1}(B) \cap (S_n^+ \cup S_n^-)).$$

We break B into two disjoint pieces: $B_+ = \{\omega \in B : \omega_0 = 1\}$ and $B_- = \{\omega \in B : \omega_0 = -1\}$. Observe that $c^{-1}(B_+) \in \mathcal{A}$ up to a set of μ_p measure zero (due to the necessity that $c^{-1}(\omega)$ be unbounded collapsible on the right.) Since any $\omega \in c^{-1}(B_+)$ satisfies $\omega_{-1} = \omega_0 = 1$, we have

$$c^{-1}(B_+) \cap S_n^+ = c^{-1}(B_+) \cap \left(\bigcap_{i=0}^{2n-1} \{\omega : \omega_i \neq \omega_{i+1}\} \right) \cap \{\omega : \omega_{2n} = \omega_{2n+1}\}.$$

By inductively applying statement (2) in the definition of μ_p (or equation 19) and shift invariance of μ_p we have $\mu_p \circ c^{-1}(B_+ \cap S_n^+) = (1-p)^{2n} p \mu_p \circ c^{-1}(B_+)$. Note also that $B_+ \cap S_n^- = \emptyset$ for all n . Therefore, by equation 22, we have

$$\frac{1}{p} \mu_p \circ c^{-1}(\{\omega \in B_+ : \omega_0 = \omega_1\}) = \left(\sum_{n=0}^{\infty} (1-p)^{2n} \right) \mu_p \circ c^{-1}(B_+) = \frac{1}{p(2-p)} \mu_p \circ c^{-1}(B_+),$$

as expected so that B_+ satisfies equation 21. The case of B_- is very much similar. But, observe that $c^{-1}(B_-) \notin \mathcal{A}$ up to measure zero, because the conditions that $\omega_0 = -1$ and ω is zero-collapsible imply that $\omega_1 = -1$. However, we do have that $\sigma(B_-) \in \mathcal{A}$.

$$c^{-1}(B_+) \cap S_n^+ = c^{-1}(B_+) \cap \left(\bigcap_{i=0}^{2n-1} \{\omega : \omega_i \neq \omega_{i+1}\} \right) \cap \{\omega : \omega_{2n} = \omega_{2n+1}\}.$$

The reader may check that $\mu_p \circ c^{-1}(B_- \cap S_n^-) = (1-p)^{2n} p \mu_p \circ c^{-1}(B_-)$, so that the same computation proves equation 21 for B replaced by B_- . Summing the equation from the B_+ case with the equation from the B_- case proves equation 21 in general. \square

Recall that if $c(\omega) = \eta$, then $\omega = \mathcal{I}_f(\eta)$ for some $f : \mathbb{Z} \rightarrow \{(-+)^n : n \geq 0\}$. See Proposition 12. The function \mathcal{I}_f inserts the word $f(0)$ between η_0 and η_1 . Note that $\iota : \omega \mapsto \frac{1}{2} \ell \circ f(0)$ defines a function from the set C of collapsible elements of Ω_\pm to \mathbb{Z} . We would like to understand the conditional expectation of ι given $c(\omega)_0$ and $c(\omega)_1$. The reason for interest in this is given by Lemma 23 and Corollary 26.

Lemma 38. *Suppose $0 < p \leq 1$, and define the map $\iota : C \rightarrow \mathbb{Z}$ as above. Let $s_0, s_1 \in \{\pm 1\}$. Then the conditional expectation of ι given $c(\omega)_0 = s_0$ and $c(\omega)_1 = s_1$ is given by*

$$(1) \quad 1 + \frac{(1-p)^2}{p(2-p)} \text{ if } s_0 s_1 = -+, \text{ and}$$

$$(2) \frac{(1-p)^2}{p(2-p)} \text{ otherwise.}$$

Proof. Let $n \in \mathbb{Z}$ with $n \geq 0$. By Corollary 13, the sets of the form

$$U(s_0, s_1, n) = \{\omega : c(\omega_0) = s_0, c(\omega_1) = s_1, \text{ and } \iota(\omega) = n\}$$

are cylinder sets. (Observe the special case $U(-, +, 0) = \emptyset$, by Corollary 13.) Let $q = \frac{1}{2-p}$. Then since each preimage under c of a point the cylinder set $\mathcal{C}(s_0 s_1)$ lies in some $U(s_0, s_1, n)$ we have

$$\sum_{n=0}^{\infty} \mu_p(U(s_0, s_1, n)) = p\mu_q(\mathcal{C}(s_0 s_1))$$

The conditional expectation of $\iota = n$ is therefore given by

$$C(s_0 s_1) = \frac{1}{p\mu_q(\mathcal{C}(s_0 s_1))} \sum_{n=0}^{\infty} n\mu_p(U(s_0, s_1, n)).$$

We can apply Corollary 13 to describe exactly which cylinder set $U(s_0, s_1, n)$ is, and apply Proposition 36 to compute its measure. This yields the following formulas.

$$C(-+) = \frac{2}{p(1-q)} \sum_{n=0}^{\infty} \frac{n}{2} p^2 (1-p)^{2n-1}. \quad C(+-) = \frac{2}{p(1-q)} \sum_{n=0}^{\infty} \frac{n}{2} p^2 (1-p)^{2n+1}.$$

$$C(--)=C(++) = \frac{2}{pq} \sum_{n=0}^{\infty} \frac{n}{2} p^2 (1-p)^{2n}.$$

□

6.2. The renormalization cocycle. Let $0 < p < 1$ and $0 < q < 1$, and define $\nu = \mu_p \times \mu_q \times \mu_N$. This is a Φ -invariant measure. In this section, we pursue the philosophy laid out beneath the Renormalization Theorem 19 to exhibit a formula for the total measure of those $(\omega, \omega', \mathbf{v})$ without stable periodic orbits.

Recall the definition of the embedding ϵ of \mathbb{R}^6 into the space of Borel measurable functions \mathcal{M} on X given above equation 15. We use L to denote $\epsilon(\mathbb{R}^6)$. First, we would like to know how to compute $\int_X \epsilon(\mathbf{p})(x) d\nu(x)$. This depends nicely on p and q , and linearly on \mathbf{p} .

Proposition 39. *Let p and q be as above and $\nu = \mu_p \times \mu_q \times \mu_N$. Then for any $\mathbf{p} \in \mathbb{R}^6$ we have*

$$\int_X \epsilon(\mathbf{p})(x) d\nu(x) = \mathbf{m}_{p,q} \cdot \mathbf{p} \quad \text{where } \mathbf{m}_{p,q} = \left(\frac{1-p}{4}, \frac{1-p}{4}, \frac{p}{2}, \frac{1-q}{4}, \frac{1-q}{4}, \frac{q}{2} \right) \in \mathbb{R}^6.$$

Proof. The i -th entry of $\mathbf{m}_{p,q}$ is just $\nu(\mathcal{S}_i)$. □

We would also like to compute the matrix M' described in Corollary 26.

Proposition 40. *We have $C(\nu, 1) \circ \epsilon(\mathbf{p}) \in L$ for all $\mathbf{p} \in L$, and $\nu \circ \rho^{-1}$ -a.e. we have $C(\nu, 1) \circ \epsilon(\mathbf{p}) = \epsilon(M_{p,q}\mathbf{p})$ where*

$$M_{p,q} = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} + \frac{(1-p)^2}{p(2-p)} \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 2 \\ 1 & 1 & 0 & 0 & 0 & 2 \\ 1 & 1 & 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} + \frac{(1-q)^2}{q(2-q)} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 1 & 0 \\ 0 & 0 & 2 & 1 & 1 & 0 \\ 0 & 0 & 2 & 1 & 1 & 0 \end{bmatrix}.$$

Proof. Let $x = (\omega, \omega', \mathbf{v}) \in X$. To apply Corollary 26, we need to know the conditional expectations for the return times $R_1(x)$ given that $\rho(x) \in \mathcal{S}_j$. By Lemma 23, this is equivalent to knowing the conditional expectation of one of $\ell \circ f(0)$, $\ell \circ f(-1)$, $\ell \circ f(0)$, or $\ell \circ f(-1)$. Here f and f' are defined so that $\mathcal{I}_f \circ c(\omega) = \omega$ and $\mathcal{I}_{f'} \circ c(\omega') = \omega'$. By Lemma 38 and shift invariance, these numbers depend only the fact that $\rho(x)$ has step type j . Moreover, the vector of values $\mathbf{m} = (m_1, \dots, m_6)$ described in Corollary 26 is given by

$$\mathbf{m} = (1, 0, 0, 1, 0, 0) + \frac{(1-p)^2}{p(2-p)}(1, 1, 1, 0, 0, 0) + \frac{(1-q)^2}{q(2-q)}(0, 0, 0, 1, 1, 1).$$

Plugging these values into the matrix in Corollary 26 produces this proposition. \square

Now we wish to restate Corollary 24 in this context. Before we do this, we apply a change of coordinates. For real numbers $m, n \geq 0$, define

$$(23) \quad p(m) = \frac{m}{m+1} \quad \text{and} \quad q(n) = \frac{n}{n+1}.$$

Observe that we can restate the equation given in Theorem 37 as

$$\mu_{p(m)} \circ c^{-1} = \frac{m}{m+1} \mu_{p(m+1)}$$

So, by induction we have $\mu_{p(m)} \circ c^{-k} = \frac{m}{m+k} \mu_{p(m+k)}$.

Recall that NS denotes the collection of points in X without stable periodic orbits.

Lemma 41. *Suppose m and n are positive real numbers. Let $\nu = \mu_{p(m)} \times \mu_{q(n)} \times \mu_N$. Then*

$$\nu(NS) = \lim_{k \rightarrow \infty} \frac{mn}{(m+k)(n+k)} \mathbf{m}_{p(m+k), q(n+k)} \cdot \left(\left(\prod_{i=k-1}^0 M_{p(m+i), q(n+i)} \right) \mathbf{1} \right),$$

where $\prod_{i=k-1}^0 M_{p(m+i), q(n+i)} = M_{p(m+k-1), q(n+k-1)} \cdots M_{p(m+1), q(n+1)} M_{p(m), q(n)}$. In this formula, $\mathbf{1} \in \mathbb{R}^6$ is the vector with all entries equal one, so that $\epsilon(\mathbf{1}) = \mathbb{1}$, the vector $\mathbf{m}_{p(m+k), q(n+k)}$ is defined as in Proposition 39, and the matrices $M_{p(n+i), q(n+i)}$ are defined in Proposition 40.

We already described all the tools necessary to reformulate Corollary 24 in this context as above. Observe that the quantity in the limit corresponds to $\int_X C(\nu, n)(\mathbb{1}) d\nu \circ \rho^{-n}$ translated under the embedding ϵ . The only remark worth making is that

$$C(\nu, n)(\mathbb{1}) = \epsilon \left(\left(\prod_{i=k-1}^0 M_{p(m+i), q(n+i)} \right) \mathbf{1} \right)$$

by expanding out the cocycle as in Equation 13 and applying Proposition 40.

6.3. Evaluating the limit. Our goal for the remainder of this section is to prove that the limit described in Lemma 41 is zero. In this subsection, we introduce several simplifications which make this goal easier to attain.

We write $\mathcal{L}(m, n)$ for the quantity $\nu(NS)$ where $\nu = \mu_{p(m)} \times \mu_{q(n)} \times \mu_N$. Observe this is the limit described in the Lemma 41.

Proposition 42 (Simplification 1). *If $m' \geq m$ and $n' \geq n$, then $\mathcal{L}(m, n) = 0$ implies $\mathcal{L}(m', n') = 0$.*

Proof. Observe that the functions $p(m)$ and $q(n)$ are increasing, and the functions $p \mapsto \frac{(1-p)^2}{p(2-p)}$ and $q \mapsto \frac{(1-q)^2}{q(2-q)}$ are decreasing. This second map is relevant to the definition of $M_{p(m), q(n)}$. Observe then that all entries of $M_{p(m+i), q(n+i)}$ are non-strictly larger than those of $M_{p(m'+i), q(n'+i)}$ for all i . Therefore, all entries of the product $(\prod_{i=k-1}^0 M_{p(m+i), q(n+i)})\mathbf{1}$ are larger than those of $(\prod_{i=k-1}^0 M_{p(m'+i), q(n'+i)})\mathbf{1}$. Also observe that the ratio

$$\frac{mn}{(m+k)(n+k)} \mathbf{m}_{p(m+k), q(n+k)} \bigg/ \frac{m'n'}{(m'+k)(n'+k)} \mathbf{m}_{p(m'+k), q(n'+k)}$$

tends to a non-zero constant vector as $k \rightarrow \infty$, with vector division interpreted coordinatewise. \square

Proposition 43 (Simplification 2). *$\mathcal{L}(m+1, n+1) = 0$ implies $\mathcal{L}(m, n) = 0$.*

We omit the proof, because it is simpler than the last. The reader should observe that pull out the right-most matrix in the product for the $\mathcal{L}(m, n)$ case obtains a product relevant to the $\mathcal{L}(m+1, n+1)$ case.

Combining these two propositions yields the following:

Lemma 44 (Combined Simplification). *If $\mathcal{L}(1, 1) = 0$, then $\mathcal{L}(m, n) = 0$ for all $m, n > 0$.*

It turns out that there are some symmetries which appear in case we want to evaluate a limit of the form $\mathcal{L}(n, n)$. Consider the linear projection $\pi : \mathbb{R}^6 \rightarrow \mathbb{R}^2$ and section $\mathbf{s} : \mathbb{R}^2 \rightarrow \mathbb{R}^6$ satisfying $\pi \circ \mathbf{s} = \text{id}$ given by

$$(24) \quad \pi(a, b, c, d, e, f) = (a + b + d + e, c + f) \quad \text{and} \quad \mathbf{s}(a, b) = \left(\frac{a}{4}, \frac{a}{4}, \frac{b}{2}, \frac{a}{4}, \frac{a}{4}, \frac{b}{2} \right)$$

We think of \mathbf{s} and π as sending row vectors to row vectors. We observe that for all $\mathbf{w} \in \mathbb{R}^2$ and all n we have

$$(25) \quad \mathbf{s}(\mathbf{w})M_{p(n), q(n)} = \mathbf{s}(\mathbf{w}N_n) \quad \text{where} \quad N_n = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} + \frac{2}{n(n+2)} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}.$$

Therefore, we can write

$$(26) \quad \mathcal{L}(1, 1) = \lim_{k \rightarrow \infty} \frac{1}{(1+k)^2} \begin{bmatrix} \frac{1}{k+1} & \frac{k}{k+1} \end{bmatrix} \left(\prod_{n=k}^1 N_n \right) \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$

where $\prod_{n=k}^1 N_n = N_k N_{k-1} \dots N_1$.

We will further simplify this expression. Define the matrices

$$(27) \quad A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \quad \text{and} \quad B_n = \frac{1}{n}B.$$

Lemma 45 (Final Simplification).

$$\mathcal{L}(1, 1) = \frac{1}{12} \lim_{k \rightarrow \infty} \left[\begin{array}{cc} \frac{1}{k+1} & \frac{k}{k+1} \end{array} \right] \prod_{n=k}^1 \left(\frac{n+2}{n+4} A + \frac{2}{n+4} B_n \right) \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$

where the product expands as in Lemma 41 (for instance).

Proof. We will move the $\frac{1}{(1+k)^2}$ factor into the product in Equation 26. Observe that $\lim_{k \rightarrow \infty} \frac{(k+3)(k+4)}{(1+k)^2} = 1$. Furthermore, we can write $\frac{12}{(k+3)(k+4)} = \prod_{n=1}^k \frac{n+2}{n+4}$. Therefore we can rewrite Equation 26 as desired:

$$\mathcal{L}(1, 1) = \frac{1}{12} \lim_{k \rightarrow \infty} \left[\begin{array}{cc} \frac{1}{k+1} & \frac{k}{k+1} \end{array} \right] \prod_{n=k}^1 \left(\frac{n+2}{n+4} N_n \right) \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

□

Finally, we can prove the following theorem, which is just a restatement of Theorem 2.

Theorem 46. *Let $0 < p, q < 1$ and let $\nu = \mu_p \times \mu_q \times \mu_N$. Then $\nu(NS) = 0$. That is, ν -almost every $x \in X$ has a stable periodic orbit under Φ .*

Proof. By Lemmas 41 and 44, it is sufficient to prove that $\mathcal{L}(1, 1) = 0$. This amounts to evaluating the limit in Lemma 45. The main idea is to think of expanding out the product $\prod_{n=k}^1 \left(\frac{n+2}{n+4} A + \frac{2}{n+4} B_n \right)$ into 2^k terms weighted by constants. Observe that the vector $\left(\frac{n+2}{n+4}, \frac{2}{n+4} \right)$ is a probability vector, so that the sum of these constants will always be 1 for all k .

To simplify notation we write \mathbf{v}_k to denote the row vector $\left(\frac{1}{k+1}, \frac{k}{k+1} \right)$ and write $\mathbf{1}$ to denote the column vector $(1, 1)$.

Consider the alphabet $\mathcal{A} = \{a, b\}$. Given an integer $k \geq 0$, we think of an element $\alpha \in \mathcal{A}^k$ as a map $\{1, \dots, k\} \rightarrow \mathcal{A}$ given by $n \mapsto \alpha_n$. For each $k \geq 0$ we have the natural restriction map $r_k : \bigcup_{j=0}^{\infty} \mathcal{A}^{k+j} \rightarrow \mathcal{A}^k$. We can write elements of α as word in \mathcal{A} with decreasing index. For instance $\alpha = baa$ indicates that $\alpha_3 = b$ and $\alpha_2 = \alpha_1 = a$. In particular, if $\alpha \in \mathcal{A}^k$, we use $a\alpha$ and $b\alpha$ to denote the elements of \mathcal{A}^{k+1} so that $r_k(a\alpha) = r_k(b\alpha) = \alpha$, $(a\alpha)_{k+1} = a$ and $(b\alpha)_{k+1} = b$.

We define a function M from $\mathbb{N} \times \mathcal{A}$ to the space of 2×2 matrices by

$$M(n, a) = A \quad \text{and} \quad M(n, b) = B_n,$$

where A and B_n are defined as in Equation 27. Given $\alpha \in \mathcal{A}^k$ we define

$$M(\alpha) = \prod_{n=k}^1 M(n, \alpha_n) = M(k, \alpha_k) M(k-1, \alpha_{k-1}) \dots M(1, \alpha_1).$$

We define $M(\emptyset)$ to be the identity matrix, where $\emptyset \in \mathcal{A}^0$ represents the empty word.

The spaces \mathcal{A}^k come with probability measures ν_k . To define this measure consider the function $w : \mathbb{N} \times \mathcal{A} \rightarrow \mathbb{R}$ given by $w(n, a) = \frac{n+2}{n+4}$ and $w(n, b) = \frac{2}{n+4}$. Since \mathcal{A}^k is finite, we can describe the measure ν_k by the rule $\nu_k(\{\alpha\}) = \prod_{n=1}^k w(n, \alpha_n)$. Observe that these measures behave nicely with the restriction map as

$$(28) \quad \nu_k = \nu_{k+j} \circ (r_k|_{\mathcal{A}^{k+j}})^{-1}.$$

Our reason for studying these objects is that the product we would like to take a limit of can be expressed as an integral for all k :

$$(29) \quad \mathbf{v}_k \left(\prod_{n=k}^1 \left(\frac{n+2}{n+4} A + \frac{2}{n+4} B_n \right) \right) \mathbf{1} = \int_{\mathcal{A}^k} \mathbf{v}_k M(\alpha) \mathbf{1} \, d\nu_k(\alpha).$$

To simplify notation, we define $f_k(\alpha) = \mathbf{v}_k M(\alpha) \mathbf{1} \in \mathbb{R}$ whenever $\alpha \in \mathcal{A}^k$.

We make some basic observations about these functions f_k . First,

$$(30) \quad \text{If } \alpha \in \mathcal{A}^k \text{ and } \alpha_k = b, \text{ then } M(\alpha) \mathbf{1} = (f_k(\alpha), f_k(\alpha)).$$

To see this observe that $M(\alpha) = B_k M \circ r_{k-1}(\alpha)$. By the structure of B_k we have that for any $\mathbf{w} \in \mathbb{R}^2$, $B_k \mathbf{w} = (c, c)$ for some $c \in \mathbb{R}$. So we can write $M(\alpha) \mathbf{1} = (c, c)$ for some c . Then since \mathbf{v}_k is a probability vector, $f_k(\alpha) = \mathbf{v}_k M(\alpha) \mathbf{1} = c$. Our second observation is:

$$(31) \quad \text{If } \alpha \in \mathcal{A}^k \text{ and } \alpha_k = b, \text{ then } j \mapsto f_{k+j}(a^j \alpha) \text{ for } j \geq 0 \text{ is bounded and increasing.}$$

To see this, observe that Statement 30 says that $M(\alpha) \mathbf{1} = (c, c)$ for $c = f_k(\alpha) > 0$. Then, $M(a^j \alpha) = ((2j+1)c, c)$ and so

$$f_{k+j}(a^j \alpha) = \left(\frac{1}{k+j+1}, \frac{k+j}{k+j+1} \right) \cdot ((2j+1)c, c) = \frac{(3j+k+1)c}{k+j+1},$$

which is an increasing sequence converging to $3c$ as $j \rightarrow \infty$. In fact, since $f(\alpha) = c$, we have proved that

$$(32) \quad \text{If } \alpha \in \mathcal{A}^k \text{ and } \alpha_k = b, \text{ then } f_{k+j}(a^j \alpha) \rightarrow 3f_k(\alpha) \text{ as } j \rightarrow \infty.$$

Statements 31 and 32 restrict how the value of $f_{k+j}(a^j \alpha)$ grows as $j \rightarrow \infty$. In particular, to exceed $3f_k(\alpha)$ by appending letters to α , b 's must be appended at some point. We will study the times at which b 's are appended. Given $\alpha \in \mathcal{A}^k$ define $L(\alpha)$ to be the largest j with $1 \leq j \leq k$ for which $\alpha_j = b$, and define $L(\alpha) = 0$ if no such j exists. Statements 31 and 32 then imply that for any $\alpha \in \mathcal{A}^k$ we have

$$f_k(\alpha) < 3f_{L(\alpha)} \circ r_{L(\alpha)}(\alpha).$$

Note the right side is an evaluation of f on a word terminating in a b . To understand the behavior of f evaluated on such words we define the sequence of constants β_k to be the average value of $f_k(\alpha)$ taken over all $\alpha \in \mathcal{A}^k$ with $\alpha_k = b$. That is, $\beta_0 = 1$ and for $k > 0$ we have

$$(33) \quad \beta_k = \frac{1}{\nu_k \{ \alpha \in \mathcal{A}^k \mid \alpha_k = b \}} \int_{\{ \alpha \in \mathcal{A}^k \mid \alpha_k = b \}} f_k(\alpha) \, d\nu_k(\alpha).$$

We can write the integral we would like to understand can be written in terms of the β 's. Observe,

$$\int_{\mathcal{A}^k} f_k \, d\nu_k < 3 \sum_{n=0}^k P(L(\alpha) = n) \int_{\{ \alpha' \in \mathcal{A}^n : \alpha'_n = b \}} f_n(\alpha') \, d\nu_n(\alpha'),$$

where $P(L(\alpha) = n) = \nu_k \{ \alpha \in \mathcal{A}^k \mid (L(\alpha) = n) \}$ denotes the ν_k probability that $L(\alpha) = n$. For $n > 0$, we can evaluate this as

$$(34) \quad P(L(\alpha) = n) = \left(\prod_{j=n+1}^k \frac{j+2}{j+4} \right) \frac{2}{n+4} = \frac{2(n+3)}{(k+3)(k+4)}.$$

In the case of $n = 0$, we have $P(L(\alpha) = n) = \frac{12}{(k+3)(k+4)}$. Also, the integral in the sum is just β_n so that

$$\int_{\mathcal{A}^k} f_k d\nu_k < 3 \left(\frac{12}{(k+3)(k+4)} \beta_0 + \sum_{n=1}^k \frac{2(n+3)}{(k+3)(k+4)} \beta_n \right).$$

Observe the coefficients sum to one since $\sum_{n=0}^k P(L(\alpha) = n) = 1$. Also, the coefficients of β_n tend to zero as $k \rightarrow \infty$. Therefore, we have

$$(35) \quad \limsup_{k \rightarrow \infty} \int_{\mathcal{A}^k} f_k d\nu_k \leq \limsup_{k \rightarrow \infty} \beta_k.$$

So, proving $\lim_{k \rightarrow \infty} \beta_k = 0$ implies the theorem by Equation 29 and Lemma 45.

Now we wish to find an inductive formula for β_k . Observe that for all $\alpha' \in \mathcal{A}^{k-1}$,

$$\frac{1}{\nu_k\{\alpha \in \mathcal{A}^k | \alpha_k = b\}} \nu_k(b\alpha') = \nu_{k-1}(\alpha').$$

Therefore, for $k > 0$, we can simplify equation 33 as

$$(36) \quad \beta_k = \int_{\mathcal{A}^{k-1}} f_k(b\alpha') d\nu_{k-1}(\alpha').$$

Suppose $\alpha = b\alpha'$ with $\alpha' \in \mathcal{A}^{k-1}$. Let $n = L(\alpha')$, $\alpha'' = r_{L(\alpha')}(\alpha)$, and $c = f_n(\alpha'')$. Note that α'' is α with the last b and the longest prior string of a 's removed. We have

$$M(\alpha)\mathbf{1} = B_k A^{k-n-1}(c, c) = B_k((2k - 2n - 1)c, c) = \frac{2k - 2n}{k}(c, c).$$

And so by Statement 30, we know

$$(37) \quad f_k(\alpha) = \frac{2k - 2n}{k} f_n(\alpha'').$$

Also for $n > 0$, the probability that $L(\alpha') = n$ is given by $P(L(\alpha') = n) = \frac{2(n+3)}{(k+2)(k+3)}$ by Equation 34. And, in the special case of $n = 0$ we have $P(L(\alpha') = 0) = \frac{12}{(k+2)(k+3)}$. So we can evaluate the integral in Equation 36 as

$$\int_{\mathcal{A}^{k-1}} f_k(b\alpha') d\nu_{k-1}(\alpha') = \sum_{n=0}^{k-1} \frac{2k - 2n}{k} P(L(\alpha') = n) \int_{\{\alpha'' \in \mathcal{A}^n | \alpha_n = b\}} f_n(\alpha'') d\nu_n(\alpha'').$$

Plugging this and the values of $P(L(\alpha') = n)$ into Equation 33, we obtain that for $k > 0$,

$$(38) \quad \beta_k = \frac{24}{(k+2)(k+3)} \beta_0 + \sum_{n=1}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \beta_n$$

To avoid special treatment of β_0 , we define $\gamma_k = \beta_k$ for $k > 0$ and set $\gamma_0 = 2\beta_0 = 2$. Then for $k > 0$ we have

$$(39) \quad \gamma_k = \sum_{n=0}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \gamma_n$$

Define the constant s_k for $k > 0$ to be the sum of the coefficients of the above expression. That is,

$$(40) \quad s_k = \sum_{n=0}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} = \frac{2(k+1)(k+8)}{3(k+2)(k+3)}.$$

Observe that $s_k \leq 1$ for all k . In particular, $\gamma_k \leq 2s_k$ for all k . To see that $\gamma_k \rightarrow 0$ as $k \rightarrow \infty$, we will inductively prove that for all $m \geq 0$

$$(41) \quad \text{For any } m > 0, \text{ there is a } K_m \text{ such that } \gamma_k \leq 2\left(\frac{8}{9}\right)^m \text{ for } k \geq K_m.$$

This will prove the theorem by the remarks surrounding Equation 35. The above argument proves this is true for $m = 0$ with $K_m = 0$. Now suppose Statement 41 is true for $m - 1$. We will prove it for m . Observe that if you fix any n , the coefficients of γ_n in the sum of Equation 39 tend to zero as $k \rightarrow \infty$. Then, there is a constant $J_m \geq K_{m-1}$ so that $k \geq J_m$ implies

$$\sum_{n=0}^{K_{m-1}-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \gamma_n \leq \frac{2}{9} \left(\frac{8}{9}\right)^{m-1}.$$

By the inductive hypothesis, the remainder of the sum of Equation 39 satisfies

$$\sum_{n=K_{m-1}}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \gamma_n \leq 2\left(\frac{8}{9}\right)^{m-1} \sum_{n=K_{m-1}}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)}.$$

Observe that this second sum is bounded from above by s_k which tends to $\frac{2}{3}$ as $k \rightarrow \infty$. See Equation 40. We conclude that there is a constant $K_m \geq J_m$ so that $k \geq K_m$ implies

$$\sum_{n=K_{m-1}}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \gamma_n \leq \frac{14}{9} \left(\frac{8}{9}\right)^{m-1}.$$

Putting these two statements together yields that for $k \geq K_m$ we have

$$\gamma_k = \sum_{n=0}^{k-1} \frac{2(n+3)(2k-2n)}{k(k+2)(k+3)} \gamma_n \leq \frac{16}{9} \left(\frac{8}{9}\right)^{m-1} = 2\left(\frac{8}{9}\right)^m.$$

□

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